

The background of the slide is a complex network graph. It features numerous white circular nodes connected by thin, dark teal lines. The nodes are distributed across the entire width of the slide, with a higher density in the center. The background color transitions from a dark teal on the left to a lighter blue on the right.

Parameterized Algorithms

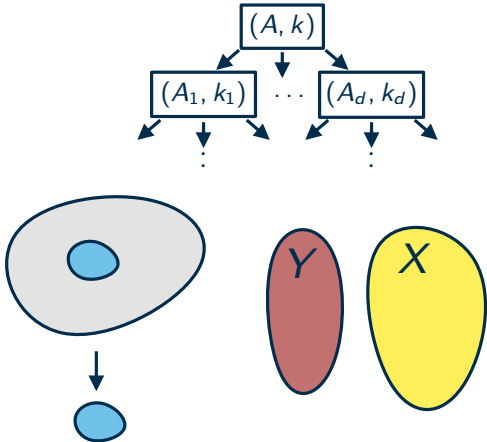
Treewidth & Dynamic Programming

Thomas Bläsius

Content

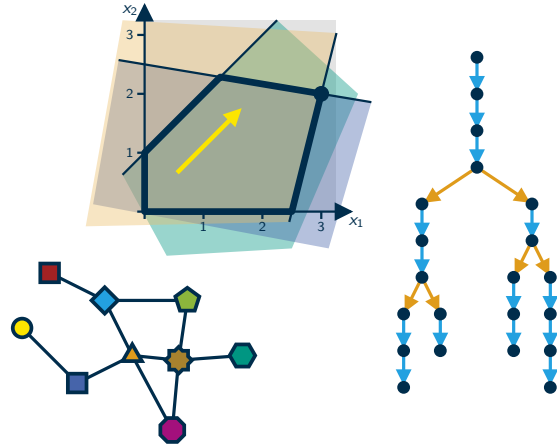
Basic toolbox

- bounded search trees
- kernelization
- iterative compression



Extended toolbox

- linear programs
- branch-and-reduce
- color coding



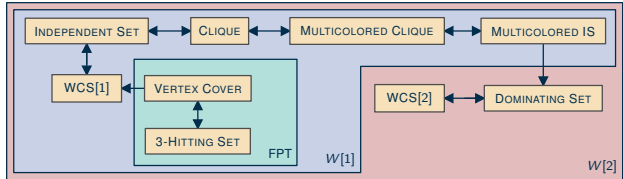
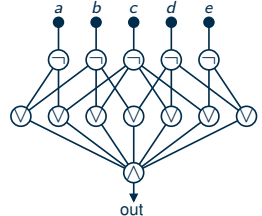
Tree width

- dynamic programming
- chordal and planar graphs
- Courcelle's theorem



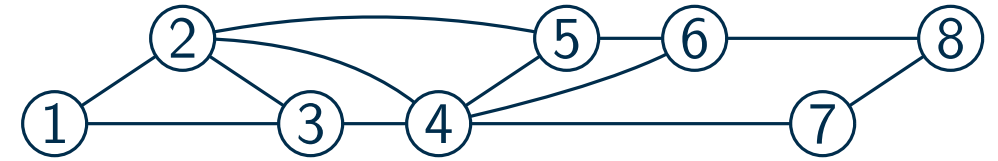
Lower bounds

- kernel lower bounds
- parameterized reductions
- circuits and the W-hierarchy
- ETH and SETH



Graphs with order

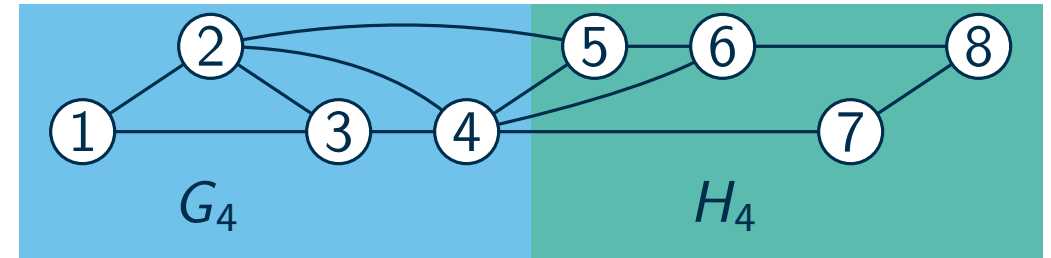
Graph $G = (V, E)$ with vertex order $V = \{v_1, \dots, v_n\}$



Graphs with order

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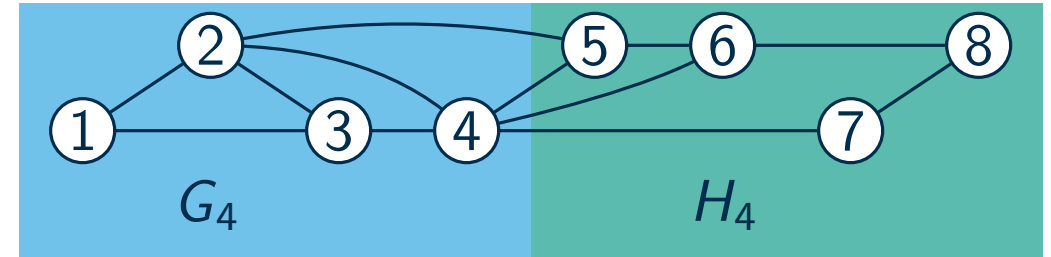
- $V_i = \{v_1, \dots, v_i\}$
- $G_i = G[V_i]$ and $H_i = G[V \setminus V_i]$



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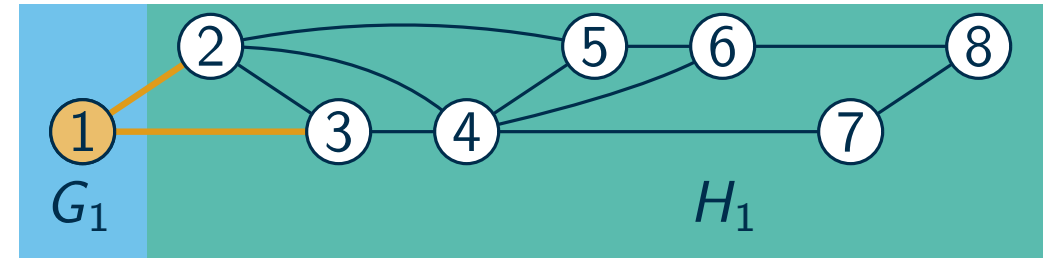


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$$k_1 = 1$$

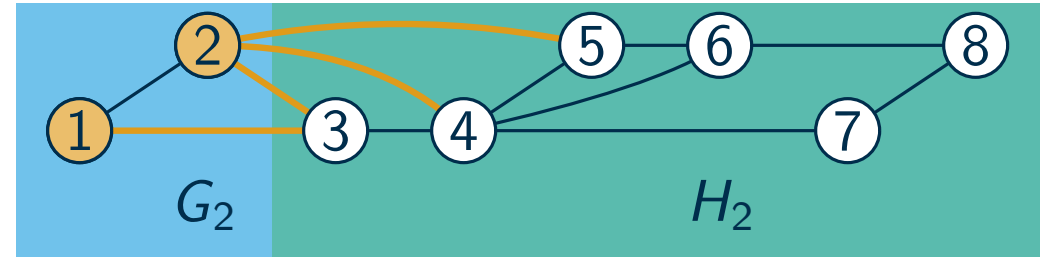


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$$k_2 = 2$$

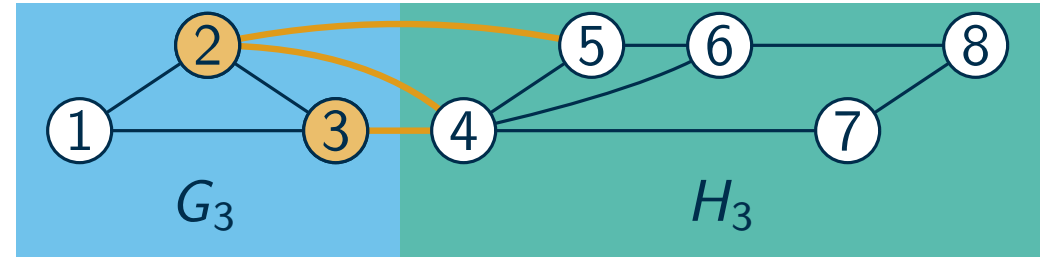


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$$k_3 = 2$$

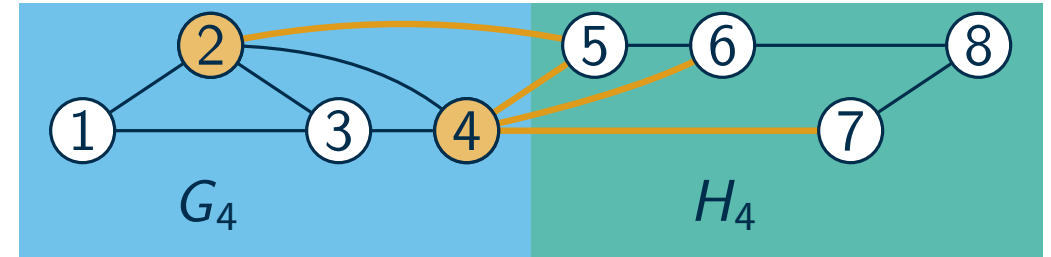


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$$k_4 = 2$$

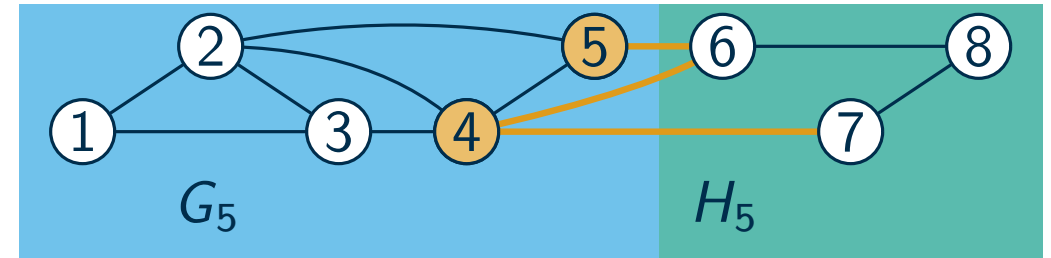


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$$k_5 = 2$$

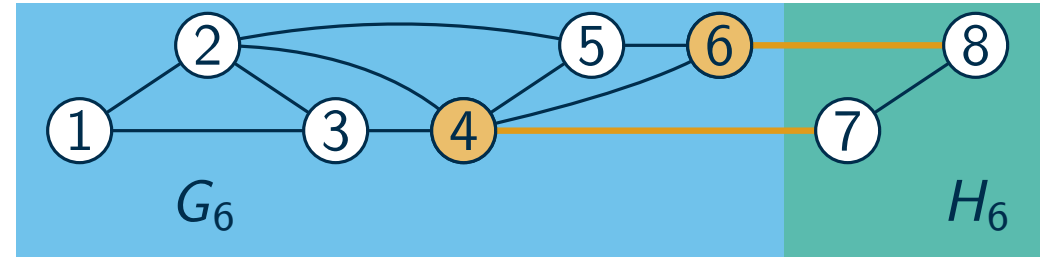


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$$k_6 = 2$$

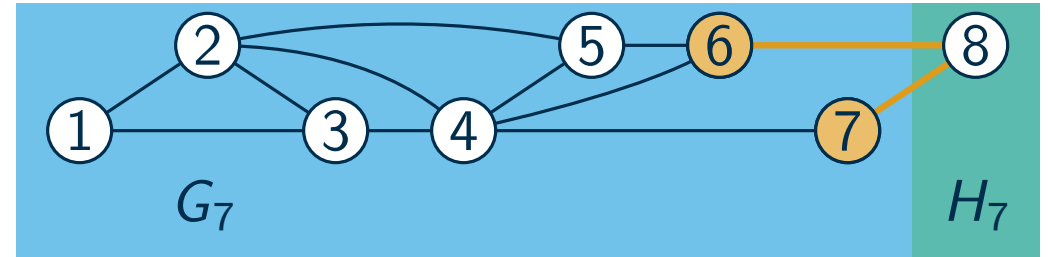


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$$k_7 = 2 \\ \Rightarrow k = 2$$

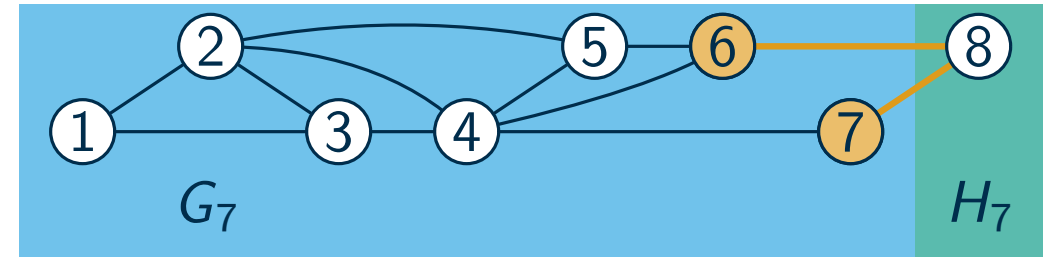


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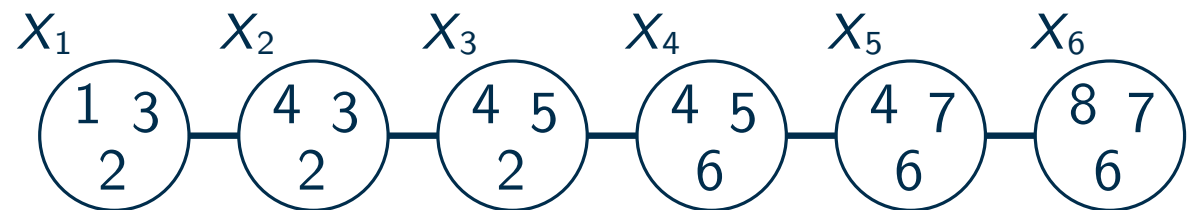
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Alternative perspective: Path decomposition

- path x_1, \dots, x_r with **bags** X_1, \dots, X_r ($X_i \subseteq V$), such that:



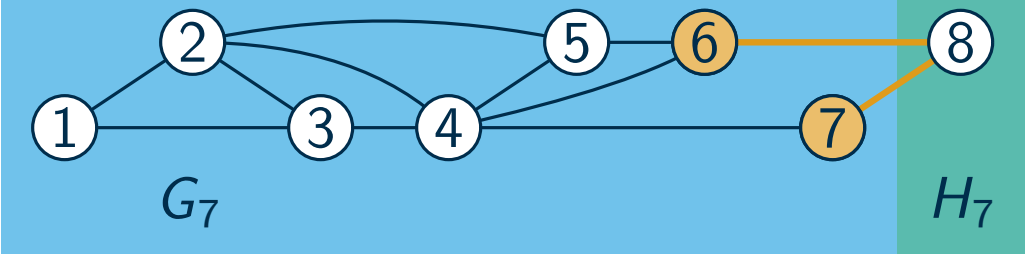
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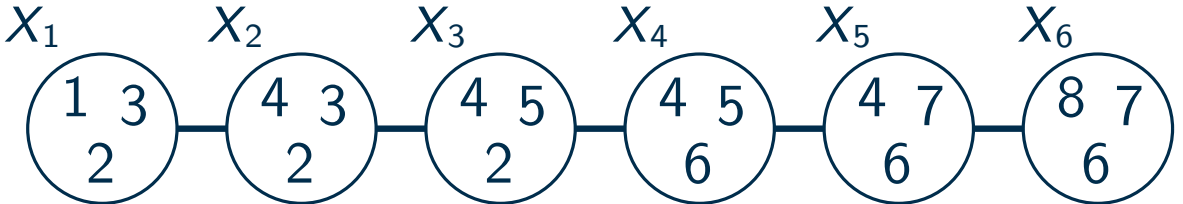
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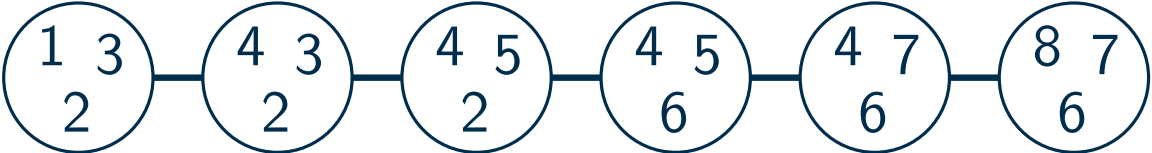
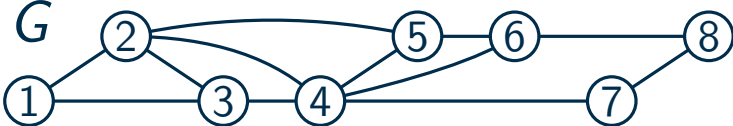
- path x_1, \dots, x_r with **bags** X_1, \dots, X_r ($X_i \subseteq V$), such that:
 - $X_1 \cup \dots \cup X_r = V$
 - $\{u, v\} \in E \Rightarrow u, v$ share a bag
 - the bags of every vertex form a subpath



Pathwidth and nice path decompositions

Pathwidth

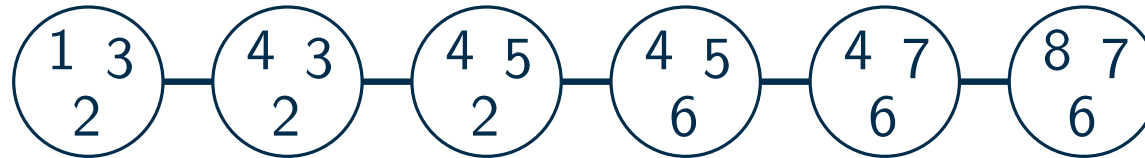
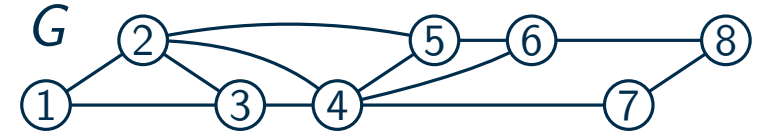
- width of a decomposition: $\max\{|X_i|\} - 1$
- pathwidth of a graph: minimum width of a decomposition



Pathwidth and nice path decompositions

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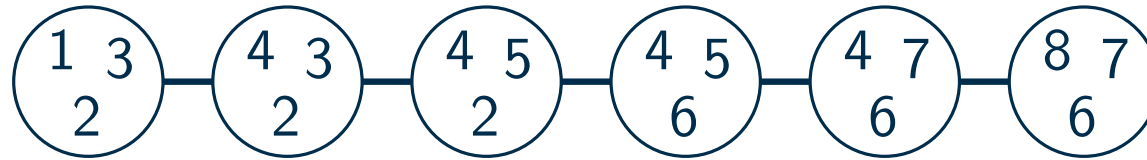
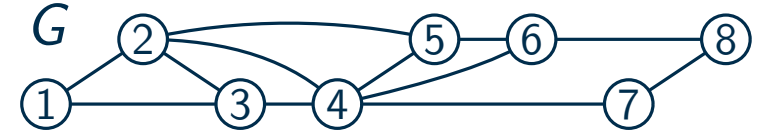
Nice path decompositions

- only two node types: introduce and forget

Pathwidth and nice path decompositions

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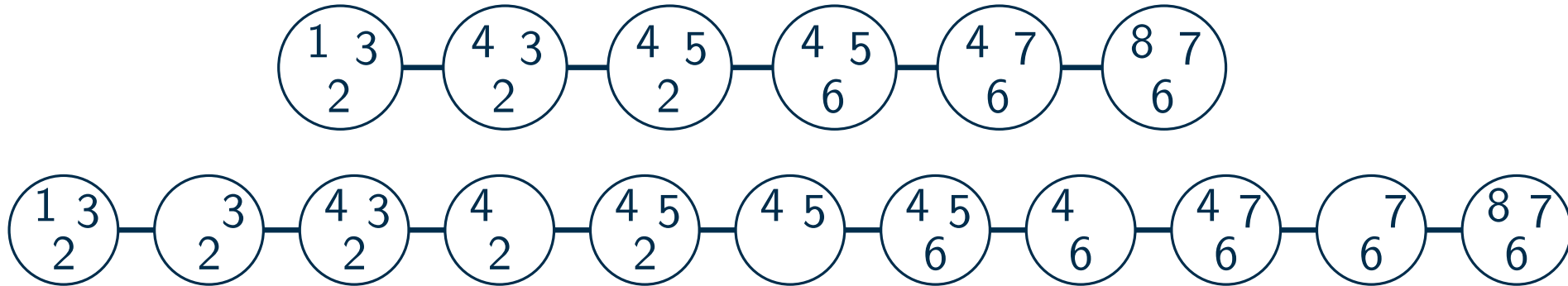
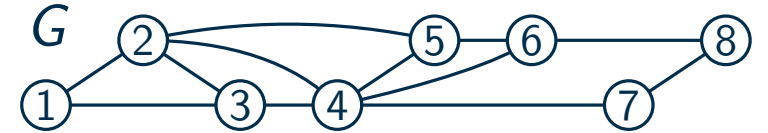
Nice path decompositions

- only two node types: introduce and forget
- x_i is introduce node if $X_i = X_{i-1} \cup \{v\}$
- x_i is forget node if $X_i = X_{i-1} \setminus \{v\}$

Pathwidth and nice path decompositions

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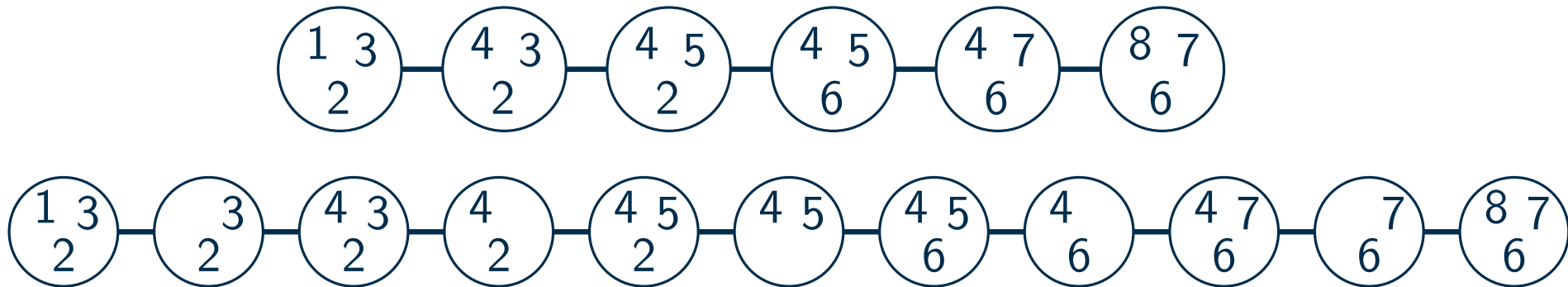
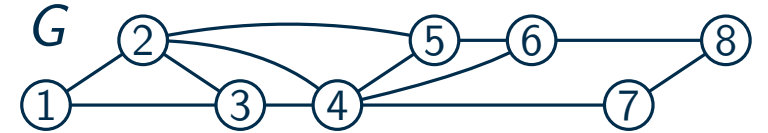
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Pathwidth and nice path decompositions

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Lemma

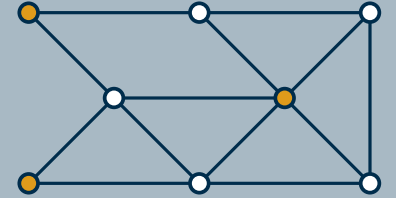
If G has a path decomposition of width p , then G has a nice path decomposition of width p .

Dynamic programming

Problem: INDEPENDENT SET

Given a graph, a parameter p , and a path decomposition of width p . Is there an independent set of size k ?

(vertices $V' \subseteq V$ with $\{u, v\} \notin E$ for $u, v \in V'$)

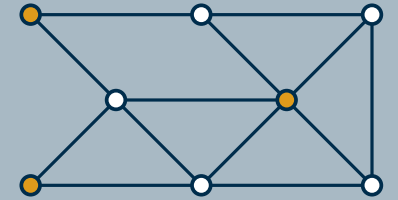


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Dynamic programming over nice path decomposition

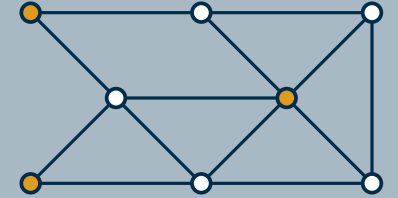
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Dynamic programming

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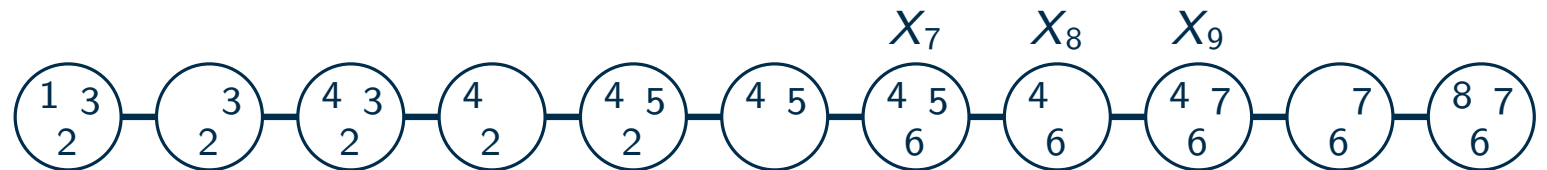
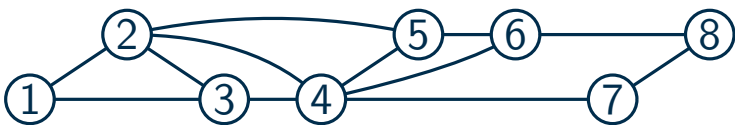
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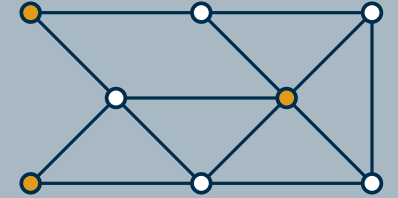
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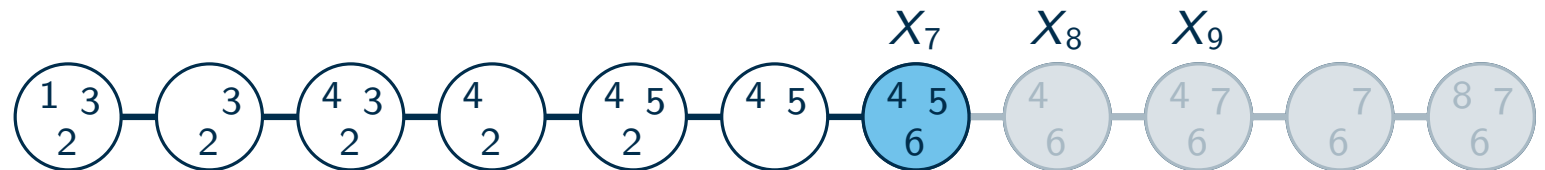
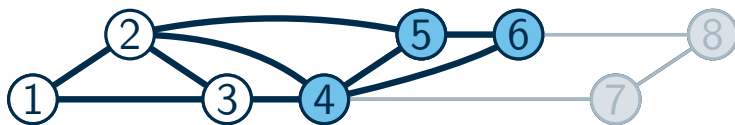
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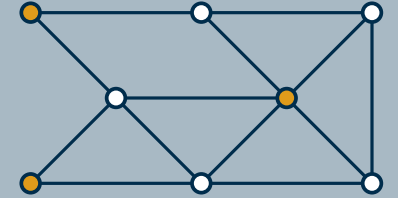
subset $X'_7 \subseteq X_7$	\emptyset	$\{4\}$	$\{5\}$	$\{6\}$	$\{4, 5\}$	$\{4, 6\}$	$\{5, 6\}$	$\{4, 5, 6\}$
largest IS size in G_7	1	2	2	2	$-\infty$	$-\infty$	$-\infty$	$-\infty$



Dynamic programming

Problem: INDEPENDENT SET

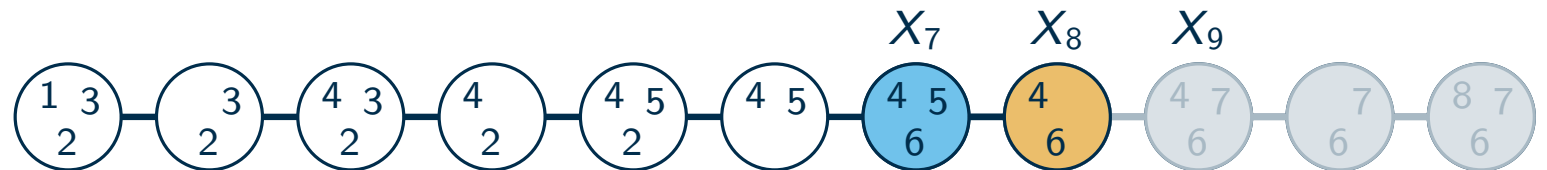
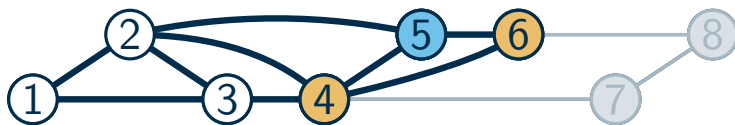
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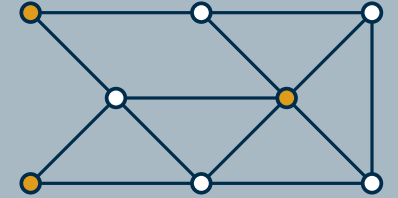
subset $X'_7 \subseteq X_7$	\emptyset	{4}	{5}	{6}	{4, 5}	{4, 6}	{5, 6}	{4, 5, 6}
largest IS size in G_7	1	2	2	2	$-\infty$	$-\infty$	$-\infty$	$-\infty$
subset $X'_8 \subseteq X_8$	\emptyset	{4}		{6}		{4, 6}		
largest IS size in G_8								



Dynamic programming

Problem: INDEPENDENT SET

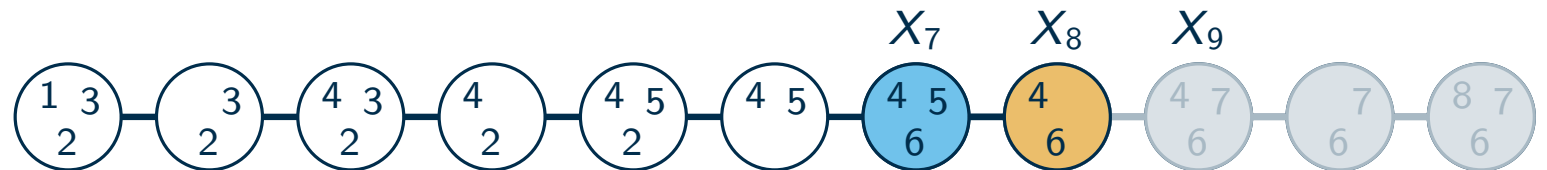
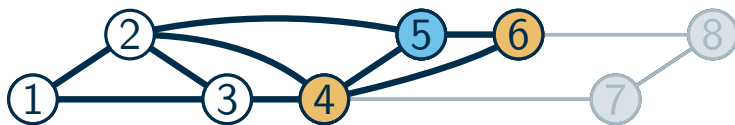
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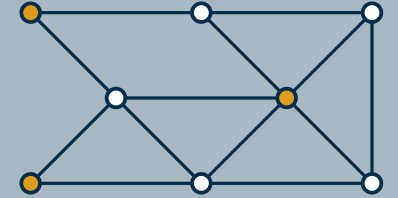
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subset $X'_8 \subseteq X_8$	\emptyset	$\{4\}$		$\{6\}$		$\{4, 6\}$		
largest IS size in G_8	2							



Dynamic programming

Problem: INDEPENDENT SET

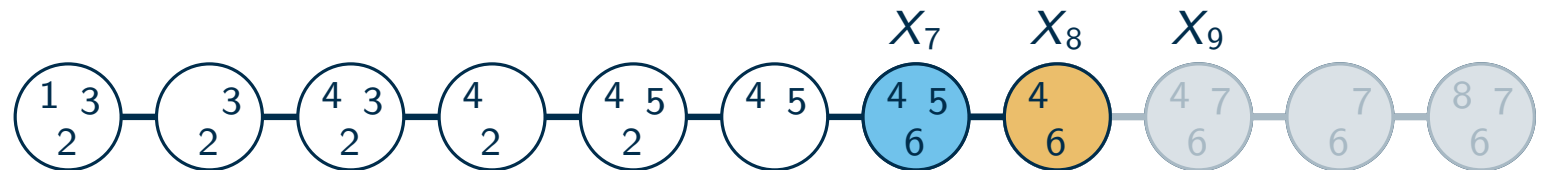
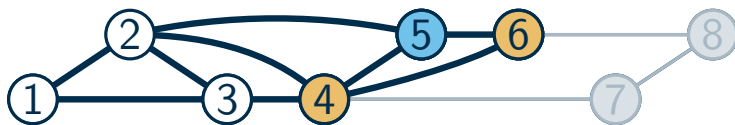
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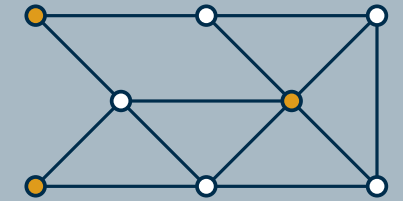
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largest IS size in G_8	2	2						



Dynamic programming

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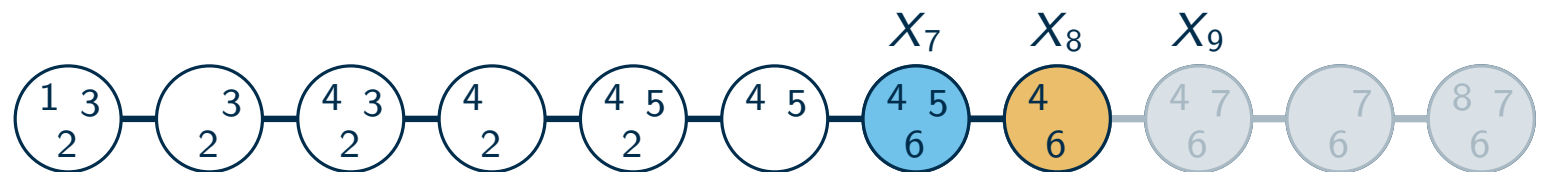
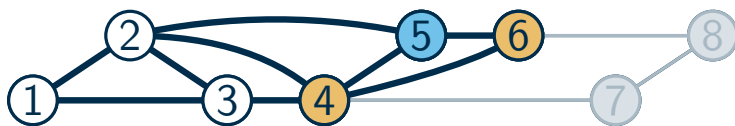
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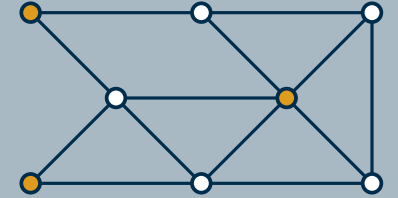
subset $X'_7 \subseteq X_7$	\emptyset	{4}	{5}	{6}	{4, 5}	{4, 6}	{5, 6}	{4, 5, 6}
largest IS size in G_7	1	2	2	2	$-\infty$	$-\infty$	$-\infty$	$-\infty$
subset $X'_8 \subseteq X_8$	\emptyset	{4}		{6}		{4, 6}		
largest IS size in G_8	2	2		2		2		



Dynamic programming

Problem: INDEPENDENT SET

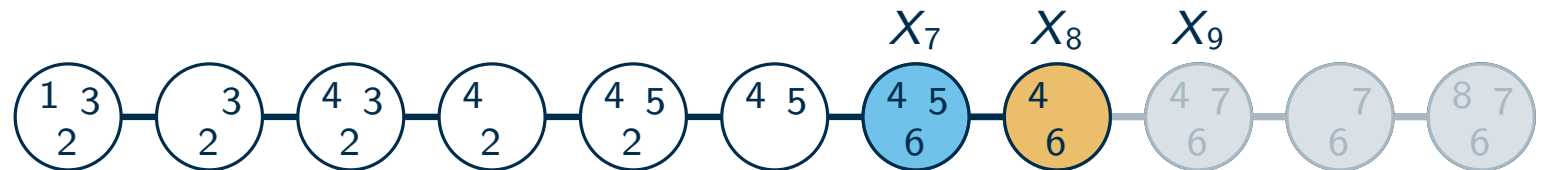
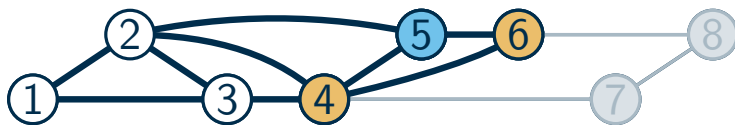
Given a graph, a parameter p , and a path decomposition of width p . Is there an independent set of size k ?
 (vertices $V' \subseteq V$ with $\{u, v\} \notin E$ for $u, v \in V'$)



Dynamic programming over nice path decomposition

- as before: $V_i = X_1 \cup \dots \cup X_i$ and $G_i = G[V_i]$
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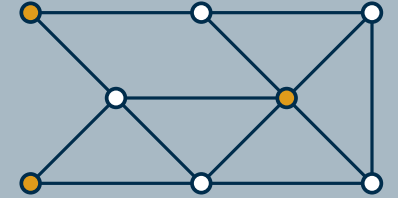
subset $X'_7 \subseteq X_7$	\emptyset	{4}	{5}	{6}	{4, 5}	{4, 6}	{5, 6}	{4, 5, 6}
largest IS size in G_7	1	2	2	2	$-\infty$	$-\infty$	$-\infty$	$-\infty$
subset $X'_8 \subseteq X_8$	\emptyset	{4}		{6}		{4, 6}		
largest IS size in G_8	2	2		2		$-\infty$		



Dynamic programming

Problem: INDEPENDENT SET

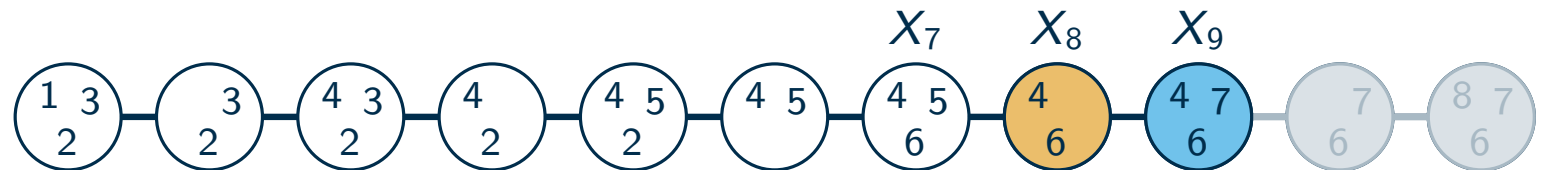
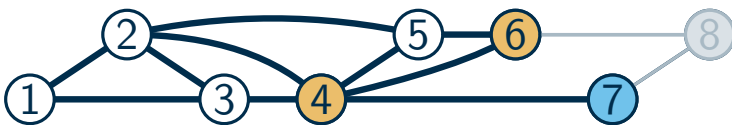
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Dynamic programming over nice path decomposition

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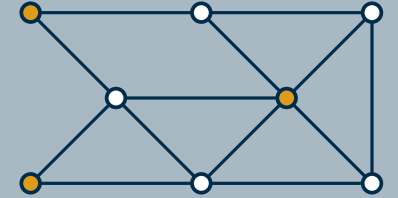
subset $X'_8 \subseteq X_8$	\emptyset	$\{4\}$	$\{6\}$	$\{4, 6\}$				
largest IS size in G_8	2	2	2	$-\infty$				
subset $X'_9 \subseteq X_9$	\emptyset	$\{7\}$	$\{4\}$	$\{4, 7\}$	$\{6\}$	$\{6, 7\}$	$\{4, 6\}$	$\{4, 6, 7\}$
largest IS size in G_9								



Dynamic programming

Problem: INDEPENDENT SET

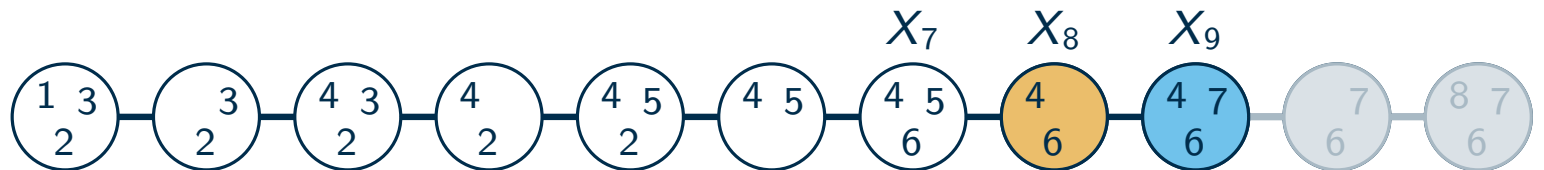
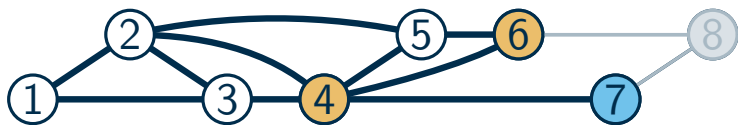
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Dynamic programming over nice path decomposition

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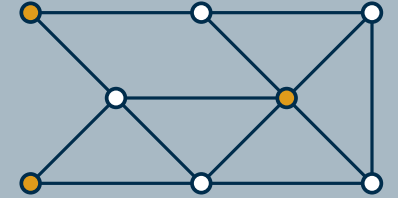
subset $X'_8 \subseteq X_8$	\emptyset	$\{4\}$	$\{6\}$	$\{4, 6\}$				
largest IS size in G_8	2	2	2	$-\infty$				
subset $X'_9 \subseteq X_9$	\emptyset	$\{7\}$	$\{4\}$	$\{4, 7\}$	$\{6\}$	$\{6, 7\}$	$\{4, 6\}$	$\{4, 6, 7\}$
largest IS size in G_9	2	3						



Dynamic programming

Problem: INDEPENDENT SET

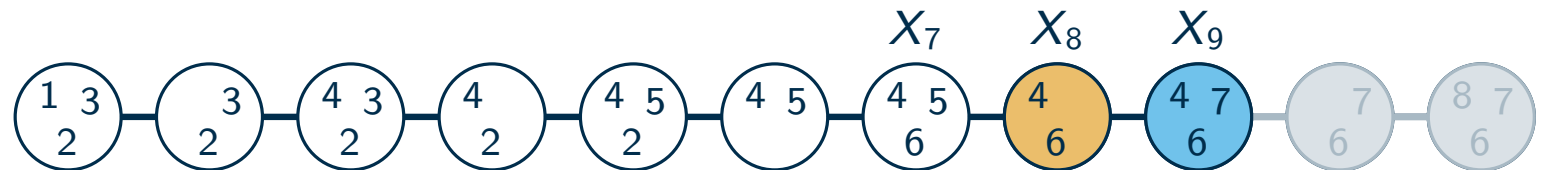
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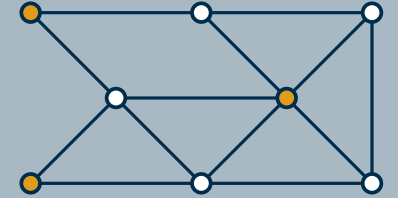
subset $X'_8 \subseteq X_8$	\emptyset	$\{4\}$	$\{6\}$	$\{4, 6\}$				
largest IS size in G_8	2	2	2	$-\infty$				
subset $X'_9 \subseteq X_9$	\emptyset	$\{7\}$	$\{4\}$	$\{4, 7\}$	$\{6\}$	$\{6, 7\}$	$\{4, 6\}$	$\{4, 6, 7\}$
largest IS size in G_9	2	3	2	$-\infty$				



Dynamic programming

Problem: INDEPENDENT SET

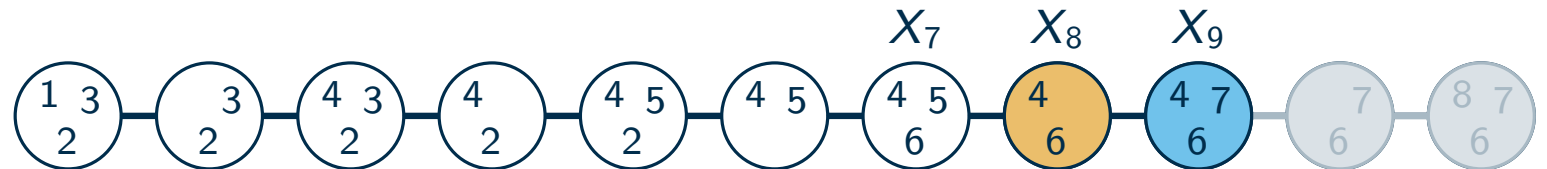
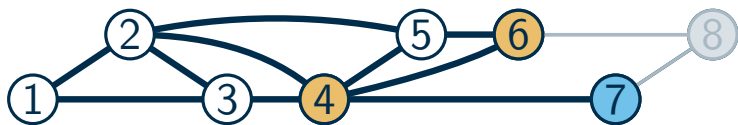
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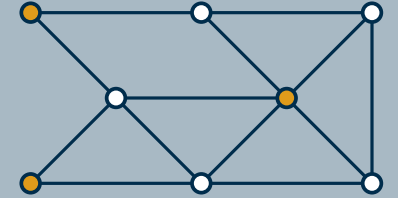
subset $X'_8 \subseteq X_8$	\emptyset	$\{4\}$	$\{6\}$	$\{4, 6\}$				
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largest IS size in G_9	2	3	2	$-\infty$	2	3		



Dynamic programming

Problem: INDEPENDENT SET

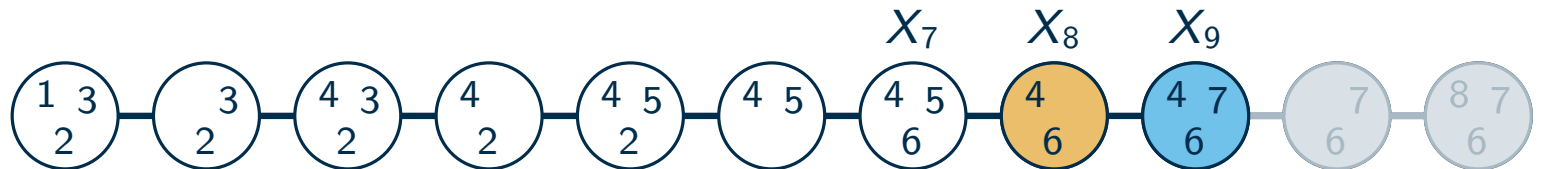
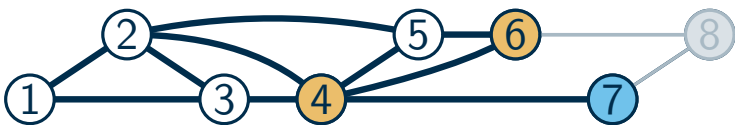
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Dynamic programming over nice path decomposition

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subset $X'_8 \subseteq X_8$	\emptyset	$\{4\}$	$\{6\}$	$\{4, 6\}$				
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largest IS size in G_9	2	3	2	$-\infty$	2	3	$-\infty$	$-\infty$



Dynamic programming

Problem: INDEPENDENT SET

Given a graph, a parameter p , and a path decomposition of width p . Is there an independent set of size k ?
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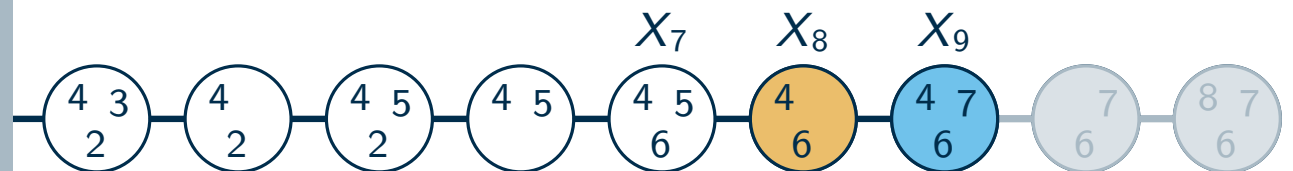
Dynamic programming over nice path decomposition

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Theorem

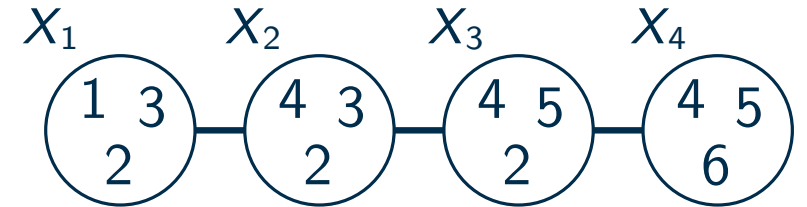
INDEPENDENT SET is FPT with respect to the pathwidth p (the DP runs in $O(2^p n^c)$).



Treewidth

Path decomposition

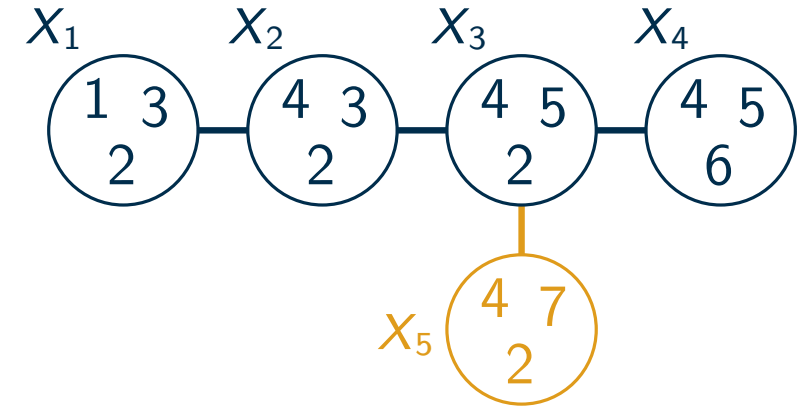
- path on nodes x_1, \dots, x_r with bags X_1, \dots, X_r , such that:
 - $X_1 \cup \dots \cup X_r = V$
 - $\{u, v\} \in E \Rightarrow u, v$ share a bag
 - the bags of every vertex form a subpath



Treewidth

Tree Path decomposition

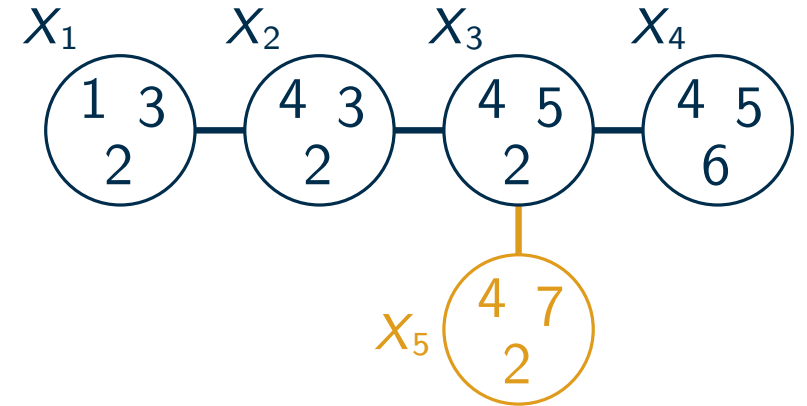
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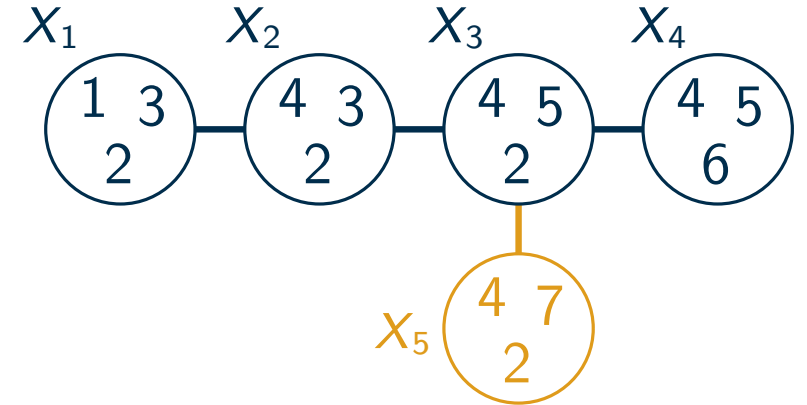
Treewidth

- width of a decomposition:
 $\max\{|X_i|\} - 1$
- treewidth of a graph:
minimum width of a decomposition

Treewidth

Tree Path decomposition

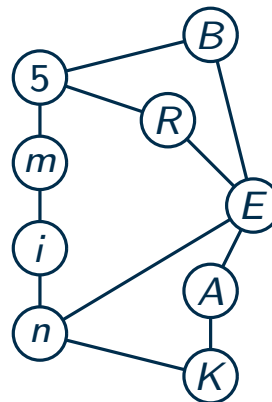
- tree path on nodes x_1, \dots, x_r with bags X_1, \dots, X_r , such that:
 - $X_1 \cup \dots \cup X_r = V$
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 - the bags of every vertex form a tree subpath



Treewidth

- width of a decomposition: $\max\{|X_i|\} - 1$
- treewidth of a graph: minimum width of a decomposition

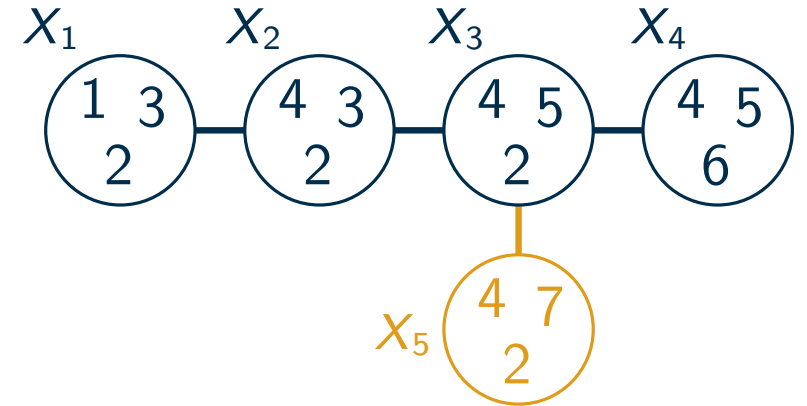
What is the treewidth of this graph?



Treewidth

Tree Path decomposition

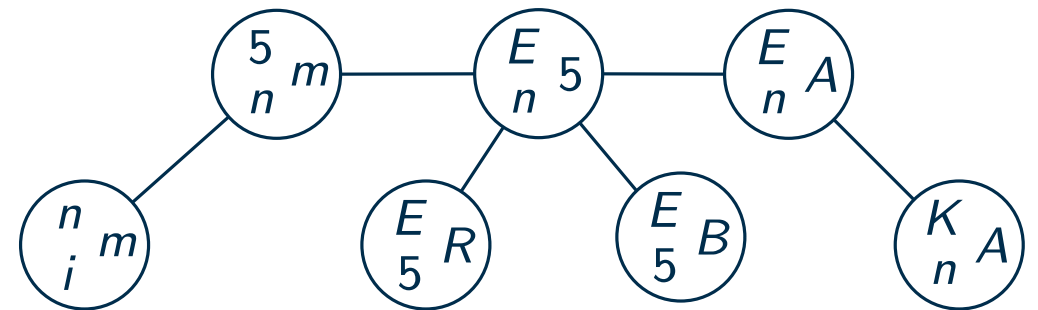
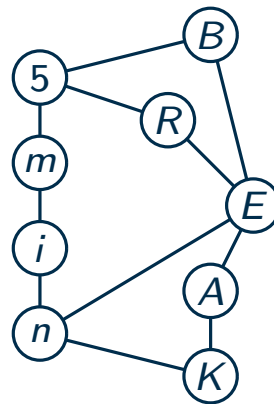
- path on nodes x_1, \dots, x_r with bags X_1, \dots, X_r , such that:
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Treewidth

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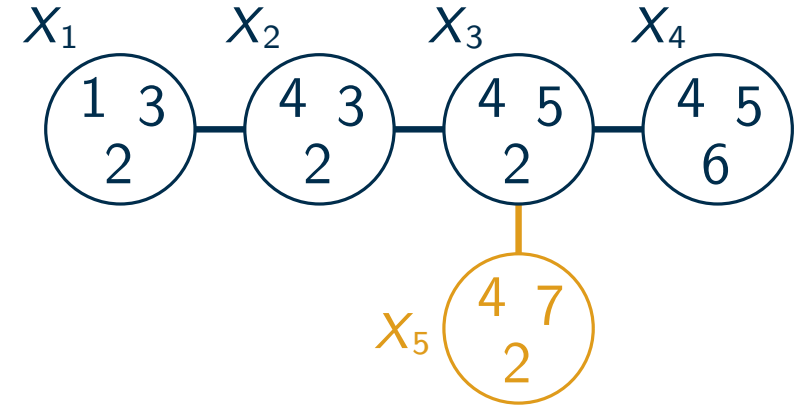


\Rightarrow treewidth 2

Treewidth

Tree Path decomposition

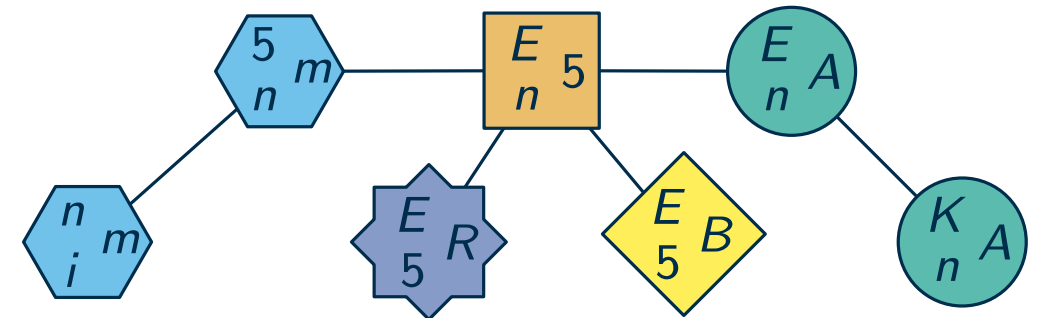
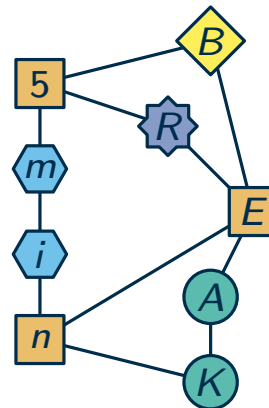
- path on nodes x_1, \dots, x_r with bags X_1, \dots, X_r , such that:
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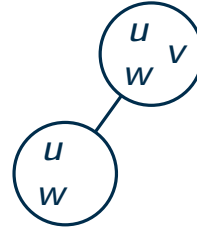
Nice tree decompositions

Three types of nodes

Nice tree decompositions

Three types of nodes

- x_i is **introduce node** if
 - x_i has exactly one child x_j and
 - $X_i = X_j \cup \{v\}$ for one vertex $v \in V$



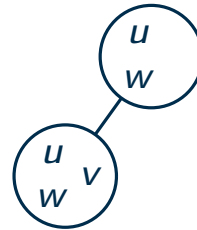
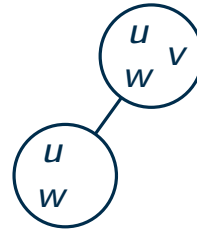
intuition: DP runs bottom-up



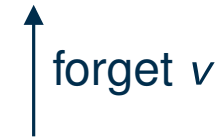
Nice tree decompositions

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intuition: DP runs bottom-up

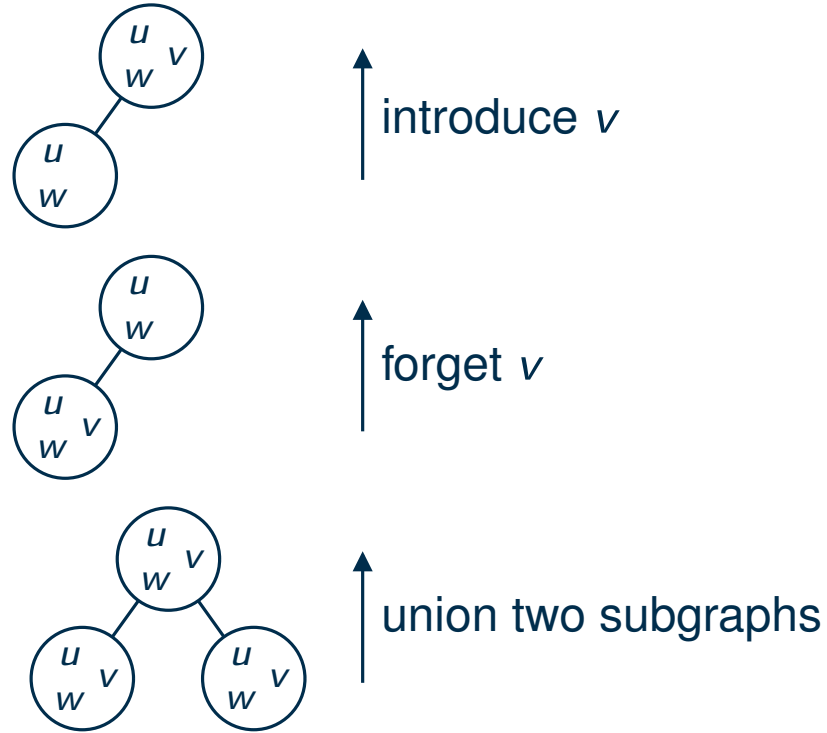


Nice tree decompositions

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- x_i is **join node** if
 - x_i has exactly two children x_j, x_k
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intuition: DP runs bottom-up

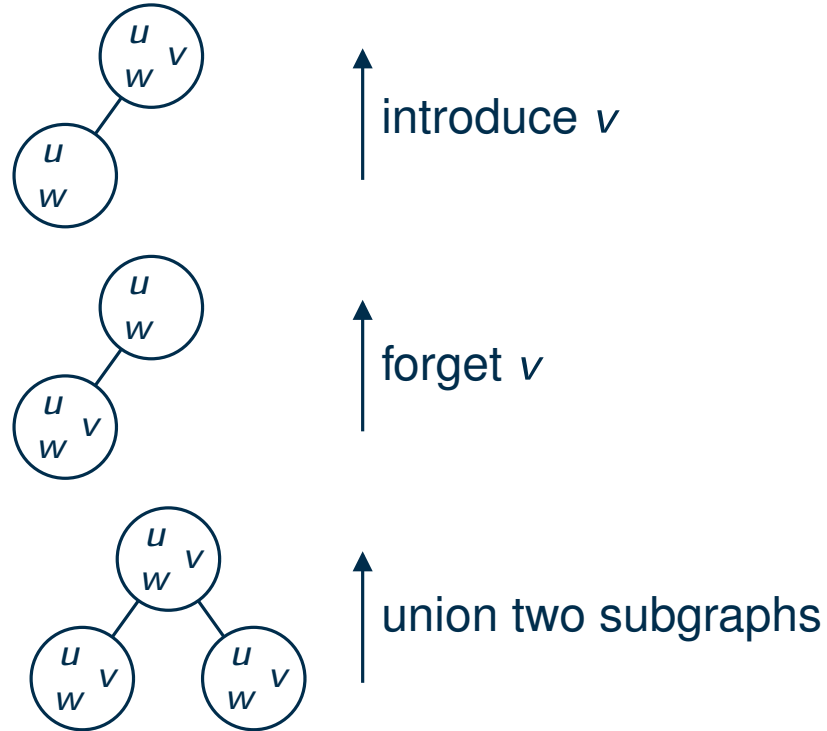


Nice tree decompositions

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Theorem

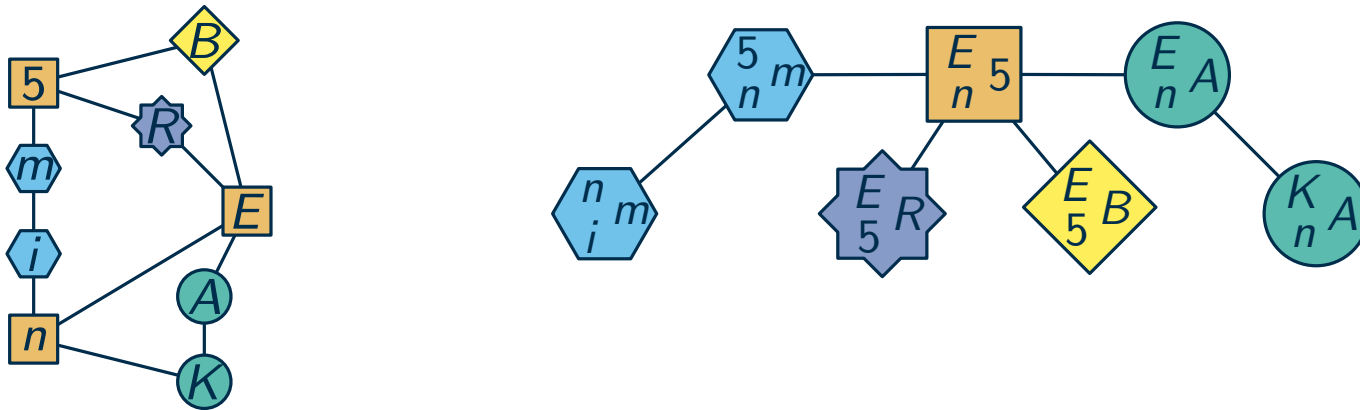
If G has treewidth t , then it has a nice tree decomposition of width t .

Making things nice

Theorem

If G has treewidth t , then it has a nice tree decomposition of width t .

Example

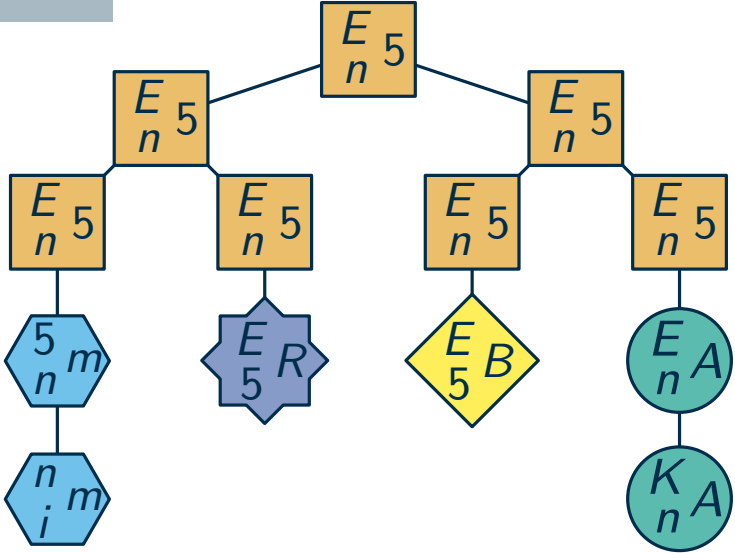
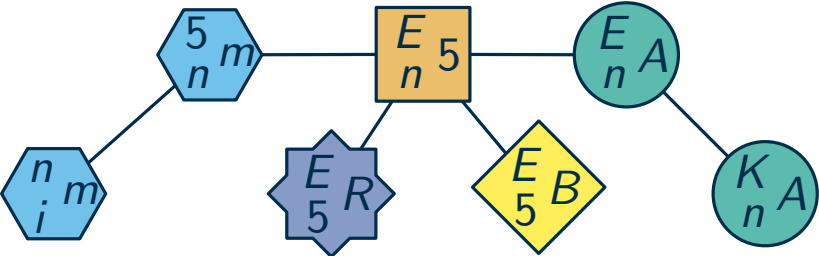
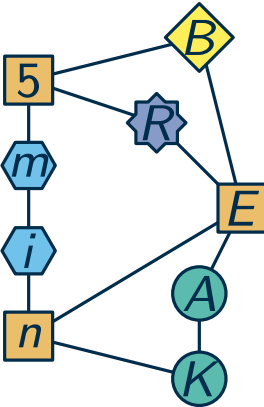


Making things nice

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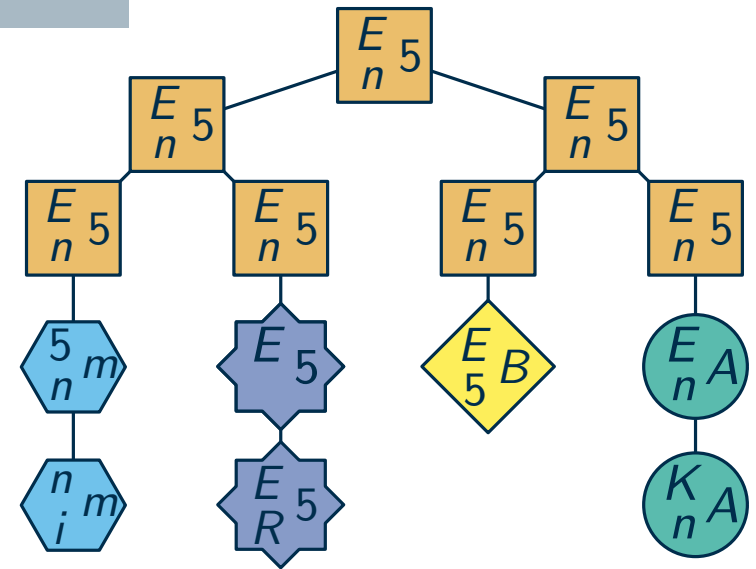
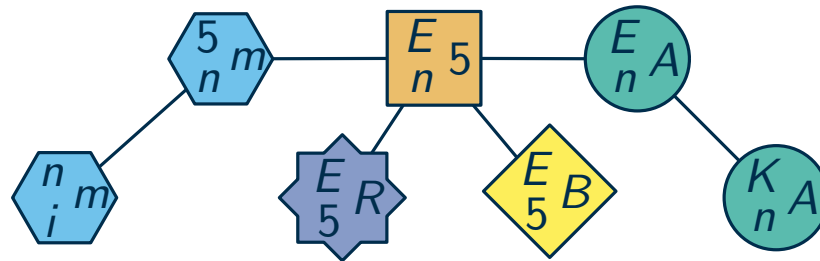
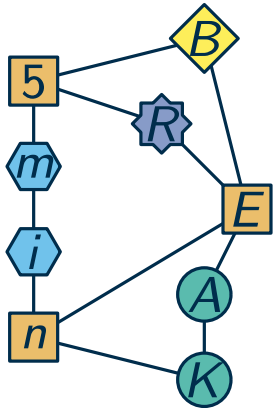


Making things nice

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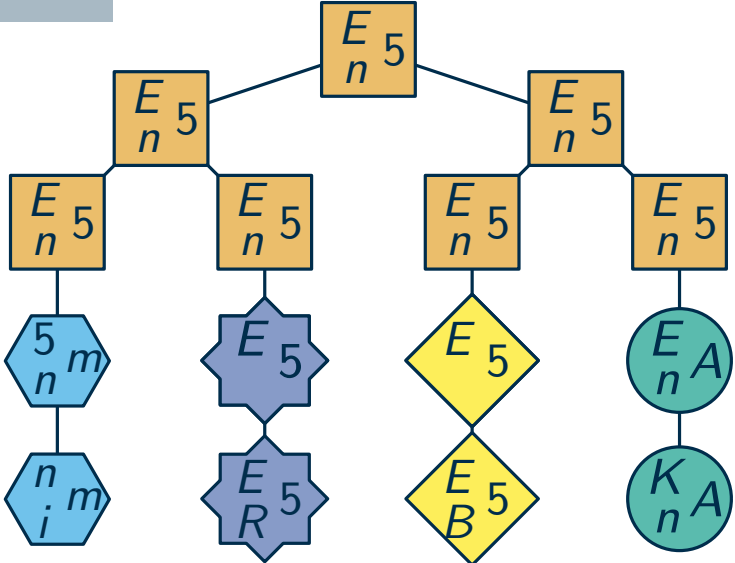
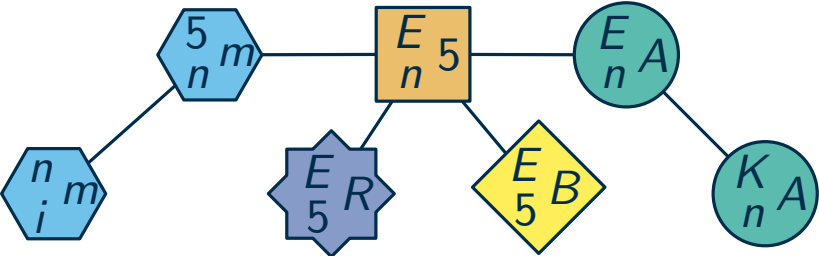
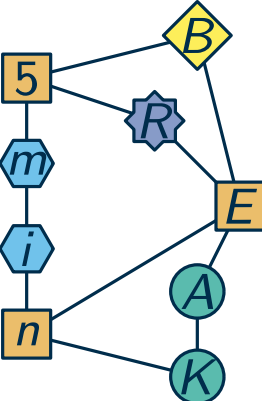


Making things nice

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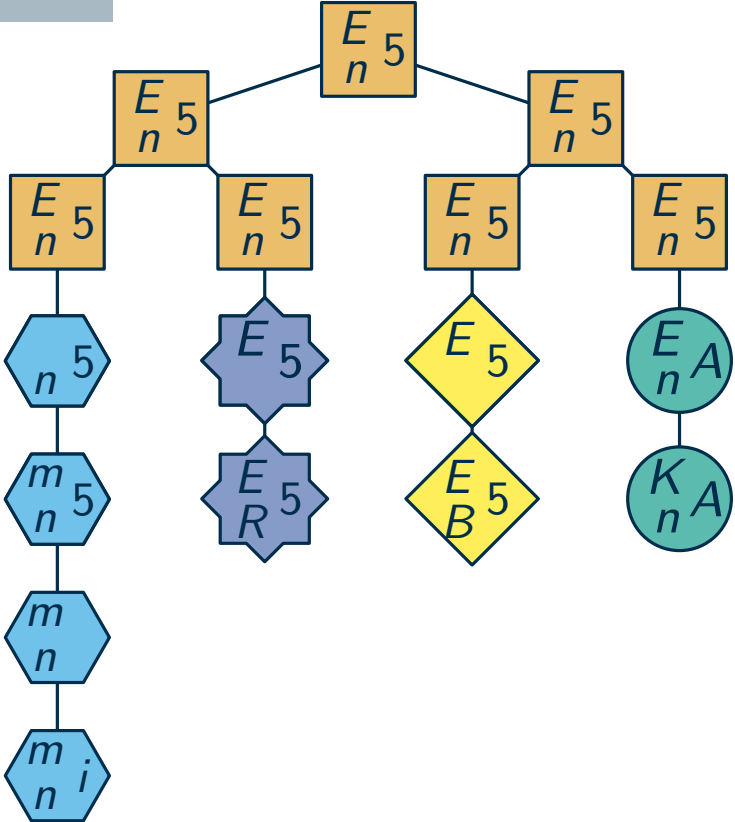
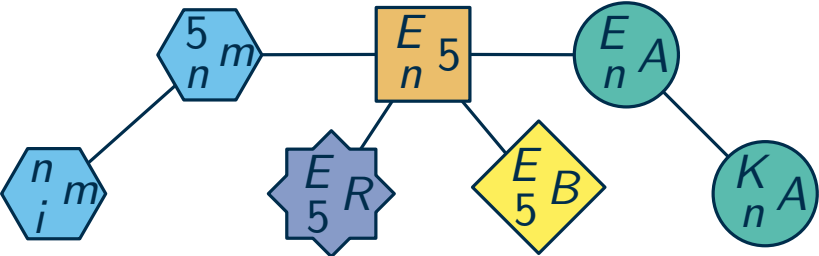
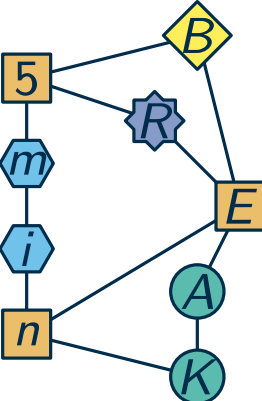


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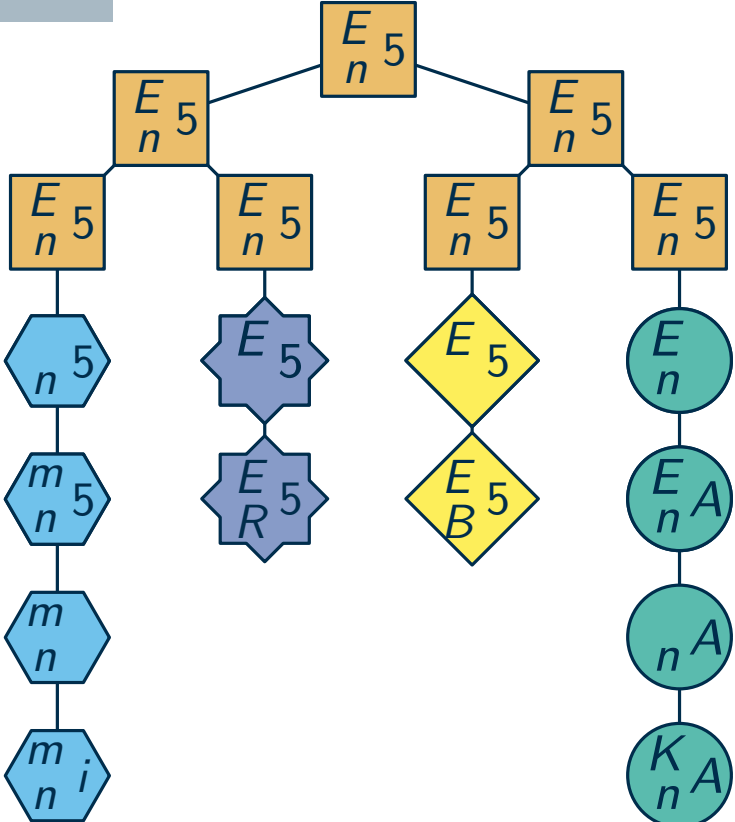
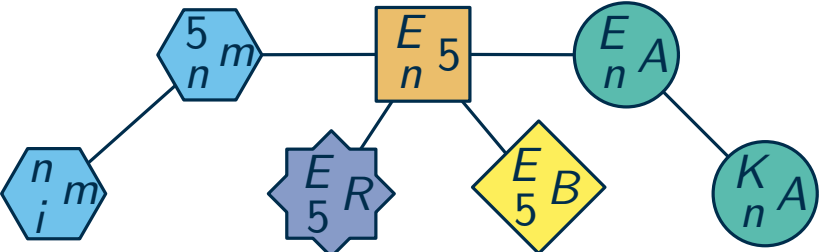
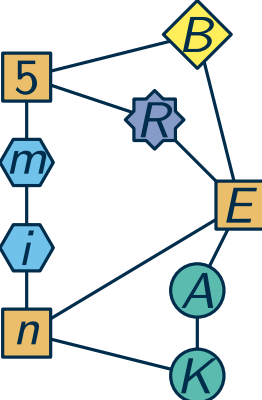


Making things nice

Theorem

If G has treewidth t , then it has a nice tree decomposition of width t .

Example



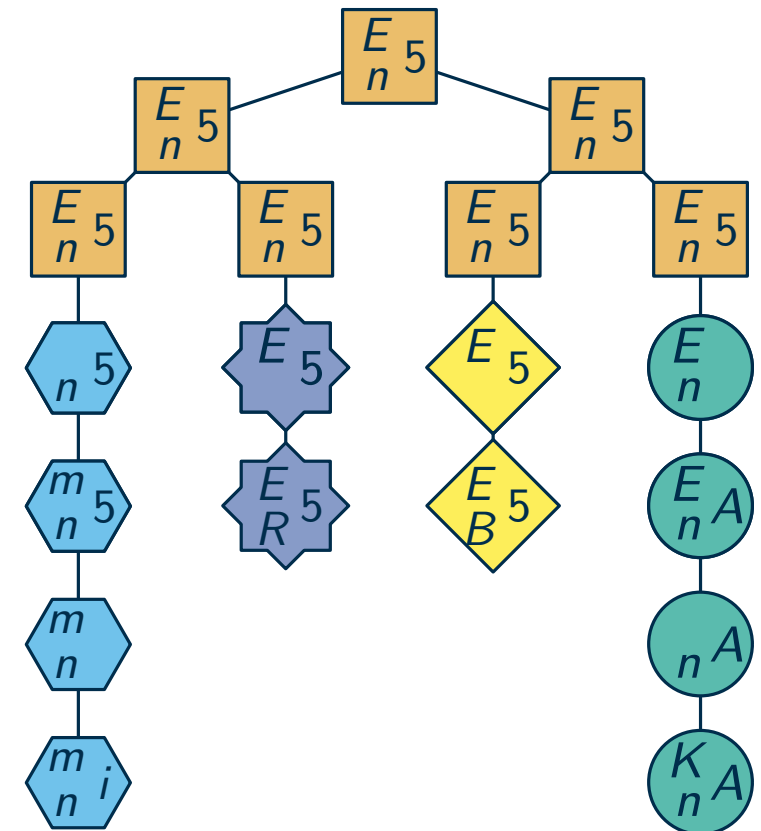
DP over nice tree decompositions

Dynamic programming over a nice tree decomposition

- introduce/forget node: as before for the path decomposition

Reminder: INDEPENDENT SET

- vertex set with no edges
- maximize size
- parameter: treewidth t



DP over nice tree decompositions

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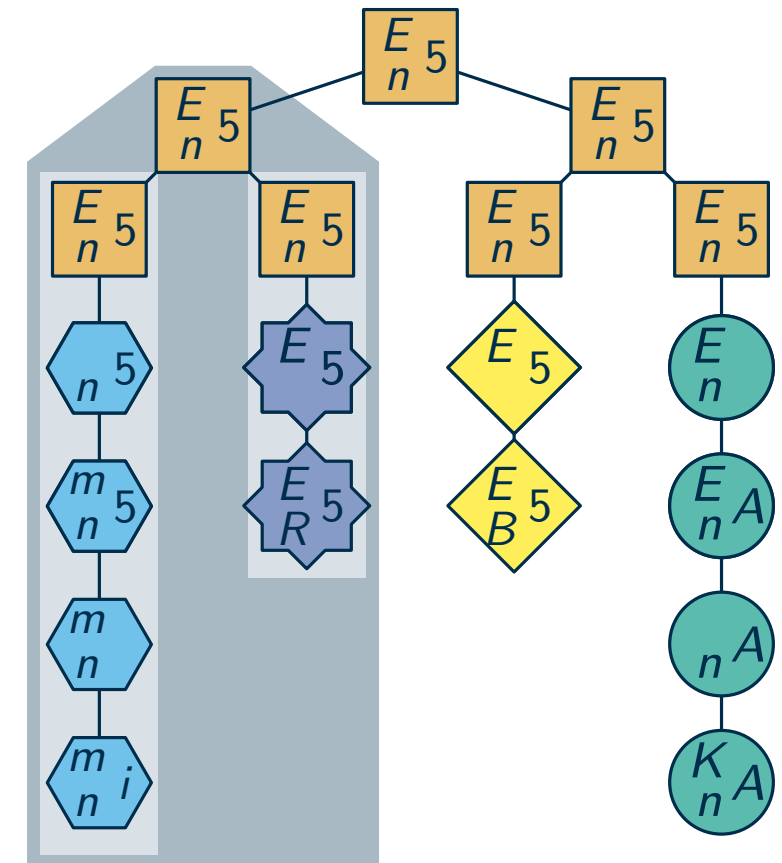
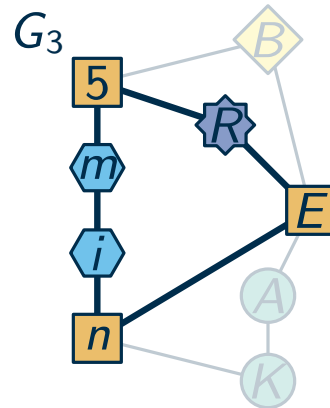
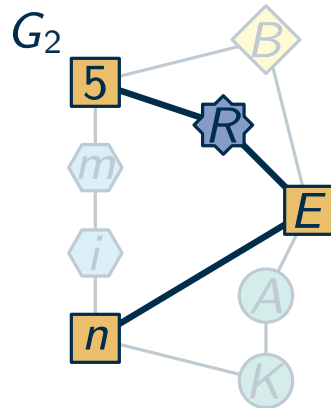
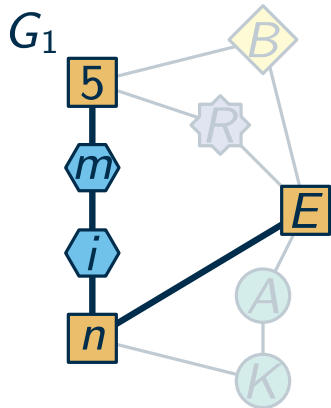
- vertex set with no edges
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Dynamic programming over a nice tree decomposition

- introduce/forget node: as before for the path decomposition
- join node: $\emptyset \quad \{E\} \quad \{5\} \quad \{n\} \quad \{E, 5\} \quad \{E, n\} \quad \{n, 5\} \quad \{E, n, 5\}$

	\emptyset	$\{E\}$	$\{5\}$	$\{n\}$	$\{E, 5\}$	$\{E, n\}$	$\{n, 5\}$	$\{E, n, 5\}$
G_1	1	2	2	2	3	$-\infty$	2	$-\infty$
G_2	1	1	1	2	2	$-\infty$	2	$-\infty$
G_3	2							

union the independent sets \Rightarrow sum values



DP over nice tree decompositions

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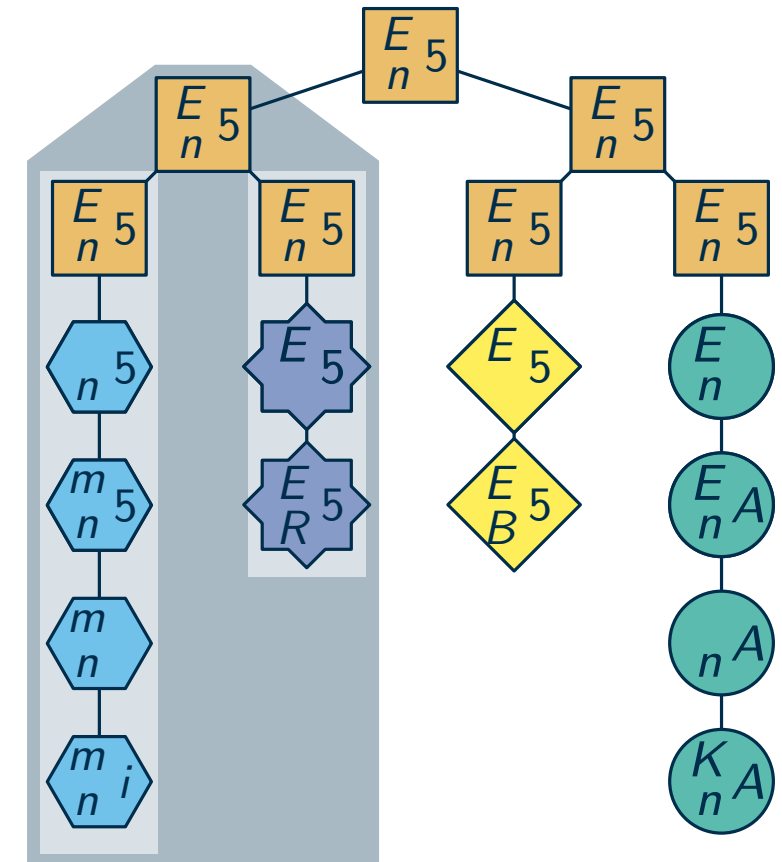
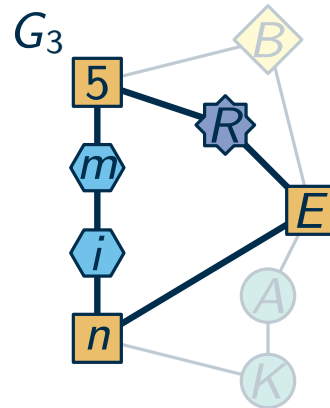
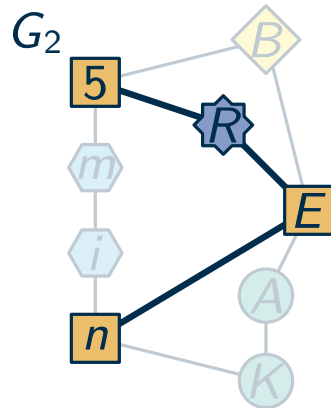
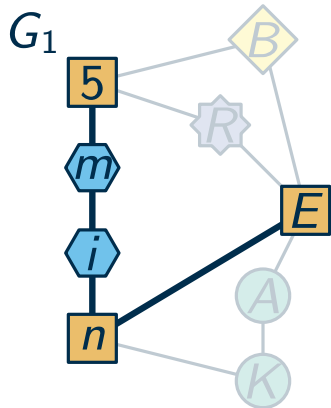
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 union the independent sets \Rightarrow sum values $-|\{E\}|$



DP over nice tree decompositions

Reminder: INDEPENDENT SET

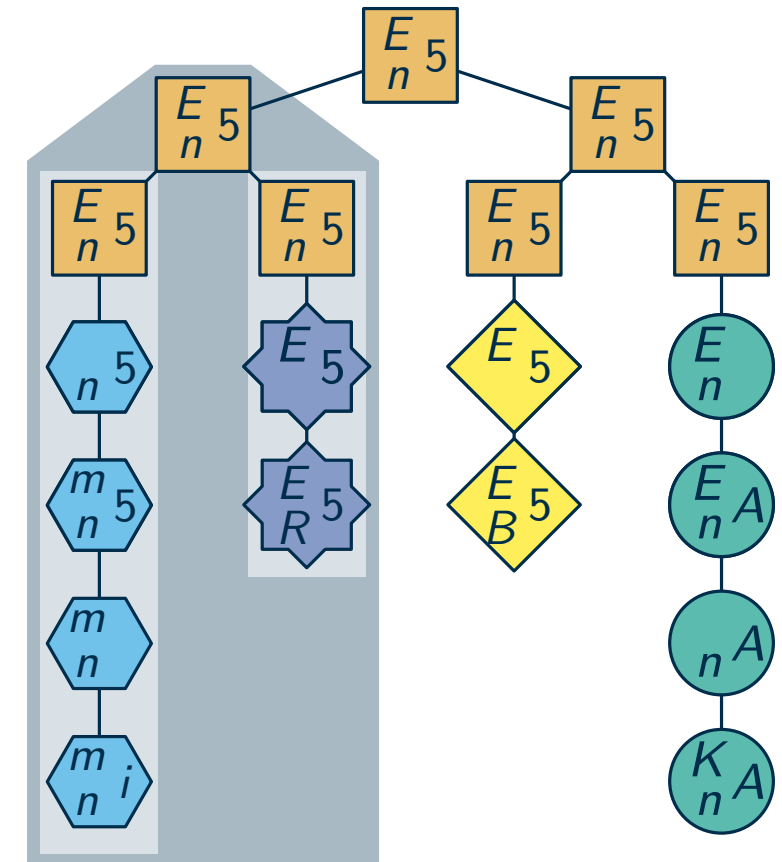
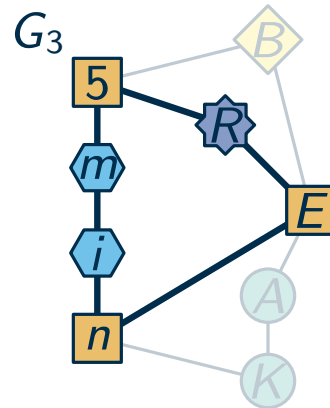
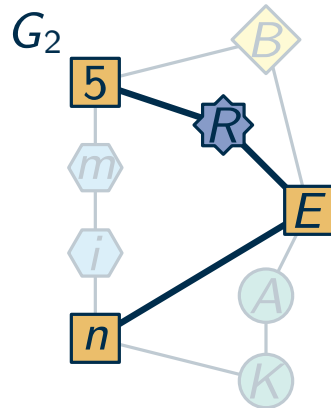
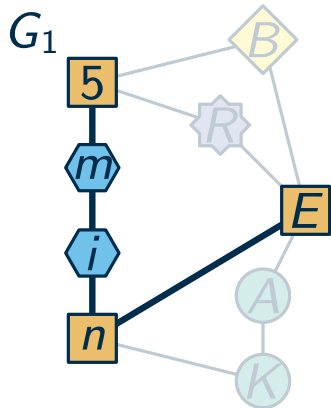
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DP over nice tree decompositions

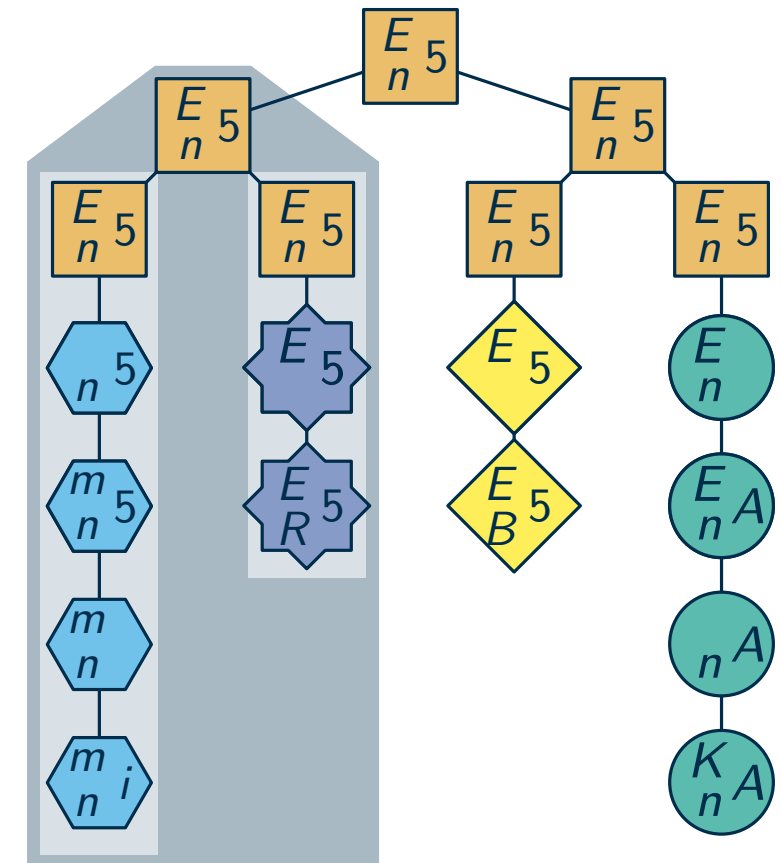
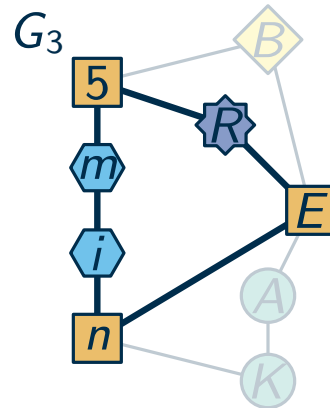
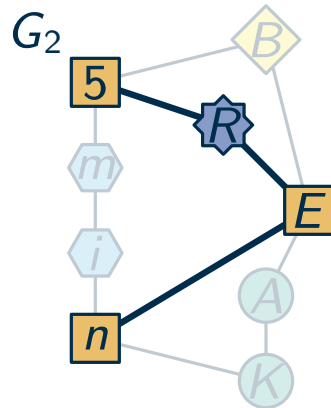
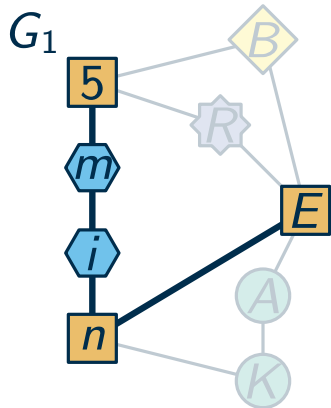
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G_3	2	2	2	3				



DP over nice tree decompositions

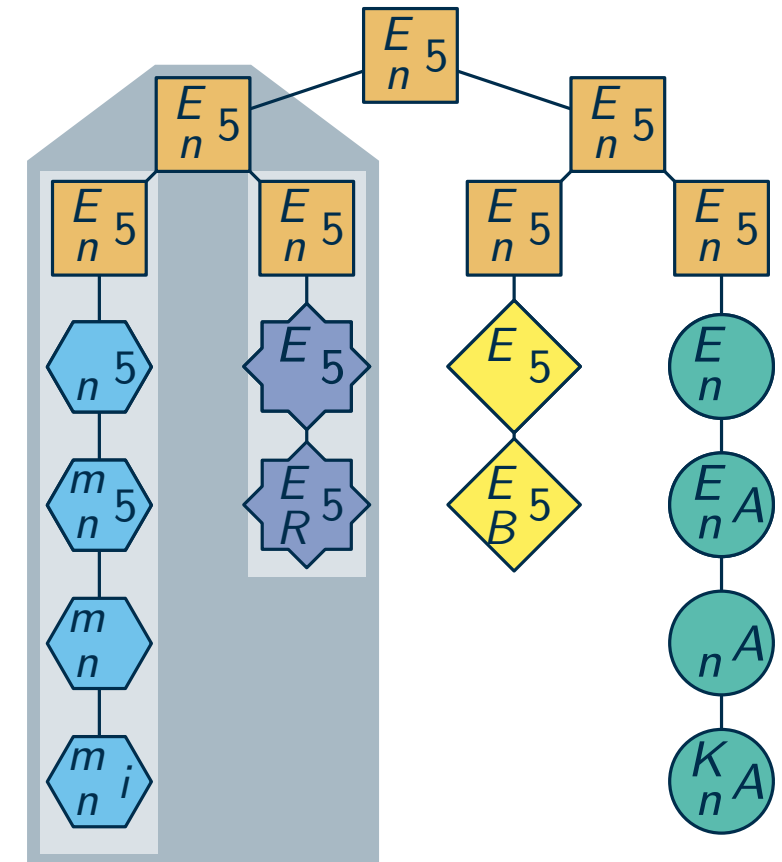
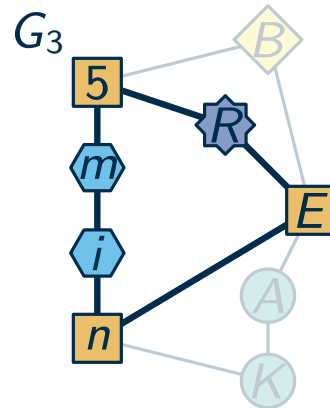
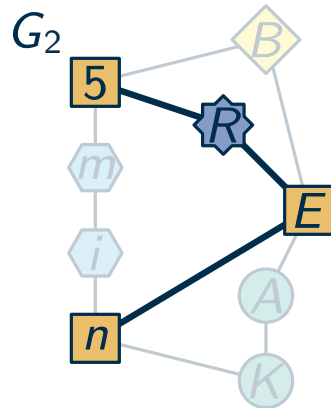
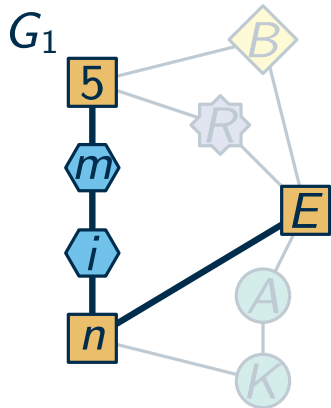
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DP over nice tree decompositions

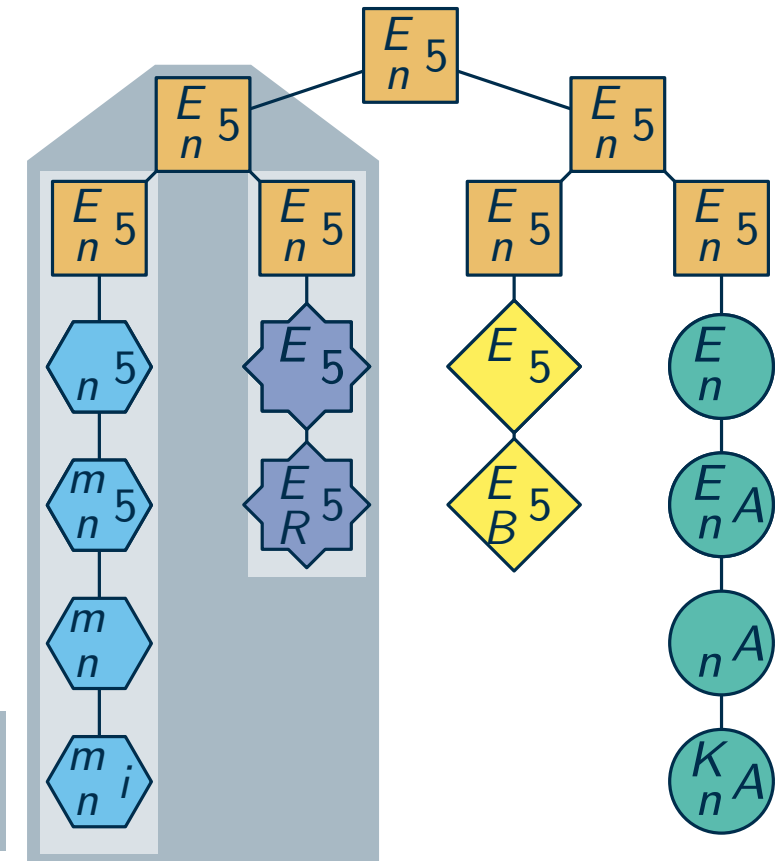
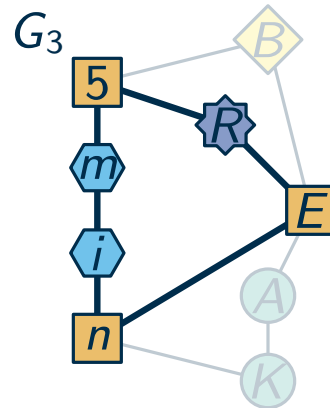
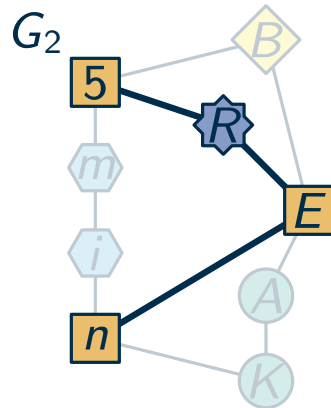
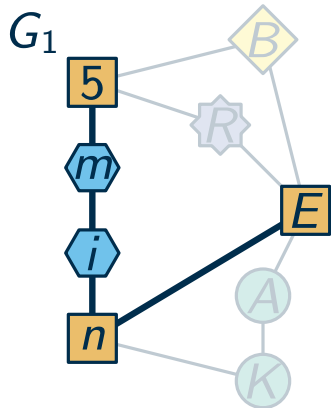
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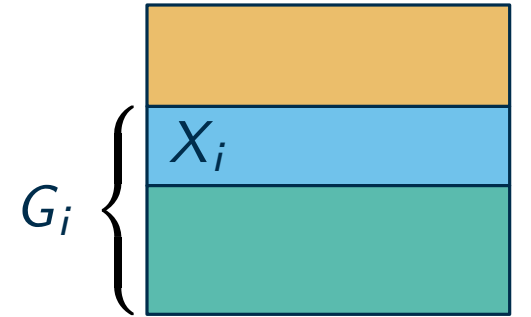


Theorem: INDEPENDENT SET is FPT with respect to treewidth.

DPs on tree decompositions

Notation and basic properties

- for node x_i : $V_i = X_i \cup \{v \in V \mid v \in X_j \text{ for successor } x_j \text{ of } x_i\}$
- $G_i = G[V_i]$ and X_i is the **interface** of G_i
- X_i separates G_i from the rest



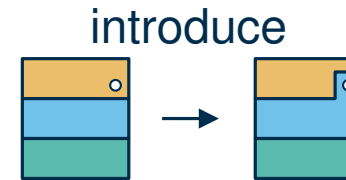
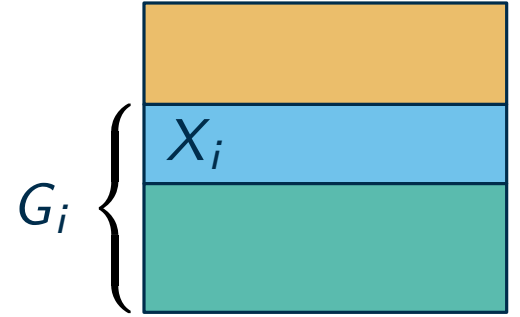
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Node types from the perspective of G_i

- **introduce**: add vertex to G_i and to the interface



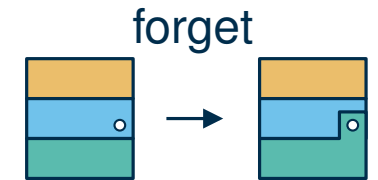
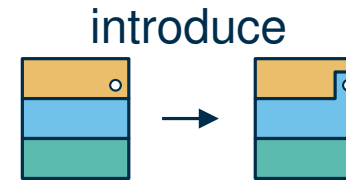
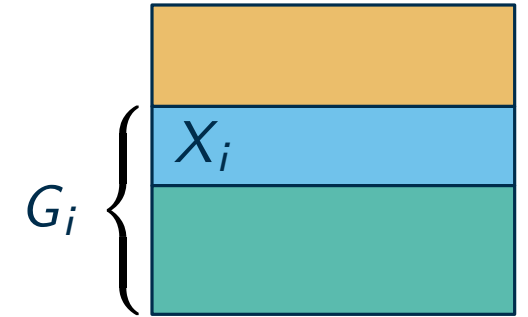
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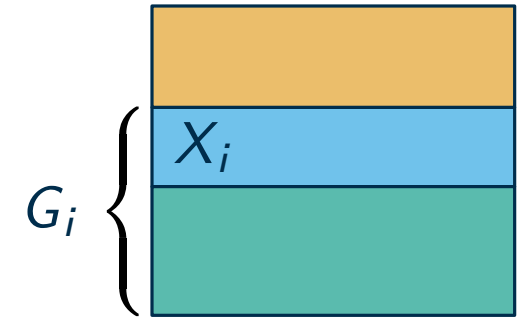
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DPs on tree decompositions

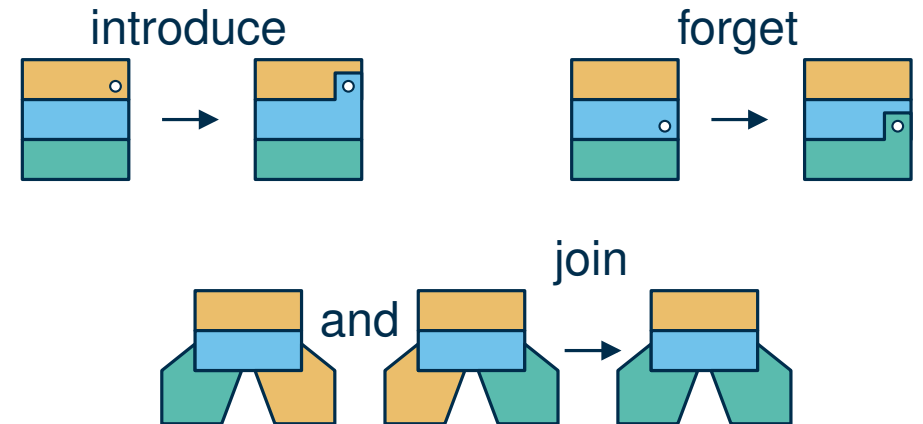
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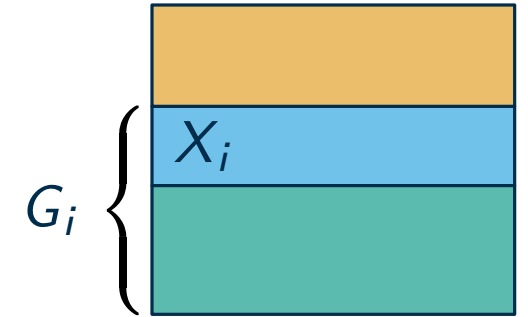
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- **join**: union two subgraphs with the same interface



DPs on tree decompositions

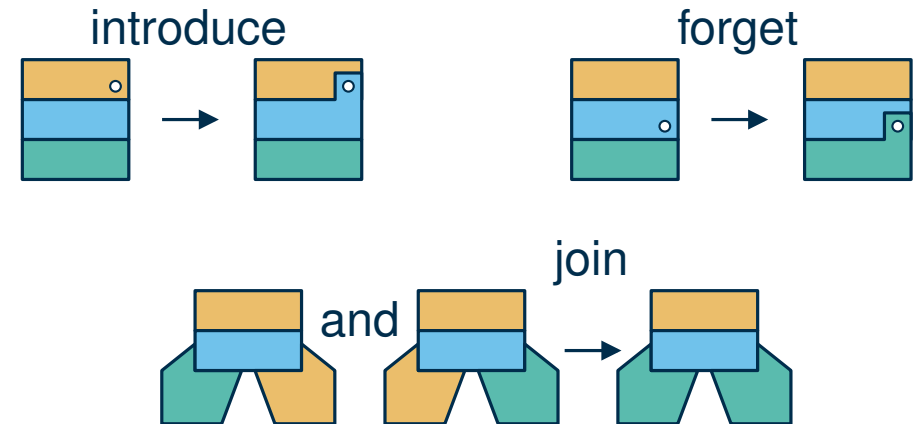
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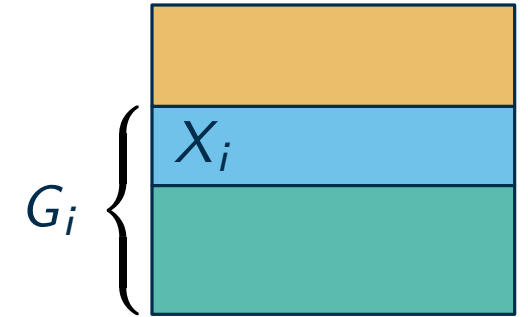
Desired properties for partial solutions on (G_i, X_i)

- for $G_i = G$, the actual solution is included

DPs on tree decompositions

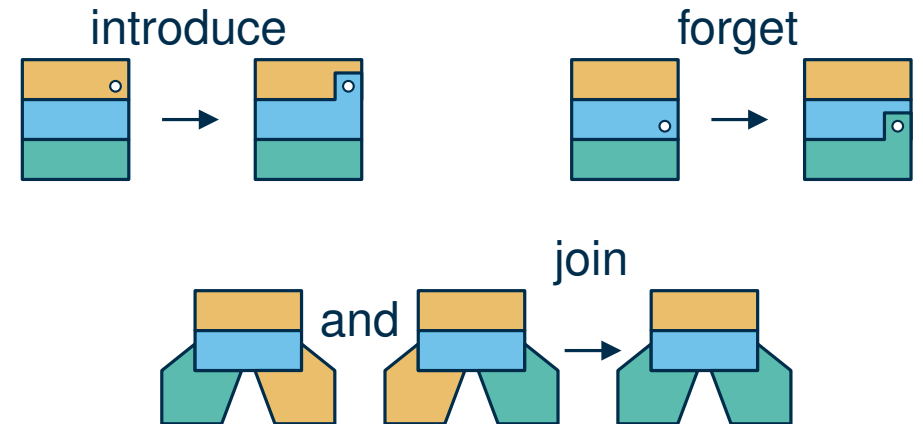
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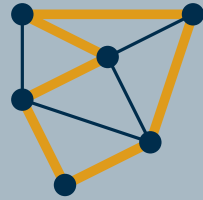
Desired properties for partial solutions on (G_i, X_i)

- for $G_i = G$, the actual solution is included
- in every step: all new partial solutions can be computed based on old ones

DP for Hamiltonian cycle – partial solutions

Problem: HAMILTONIAN CYCLE

Given a graph G . Does G have a cycle that visits all vertices?



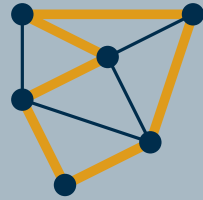
Goal

- FPT with respect to treewidth
- given: corresponding tree decomposition

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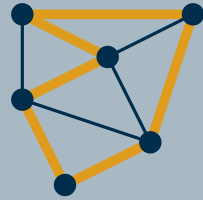
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What is a useful definition for partial solutions?

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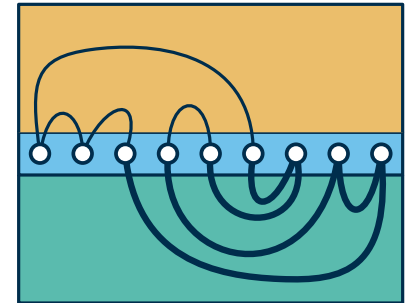


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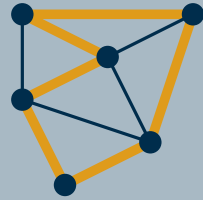
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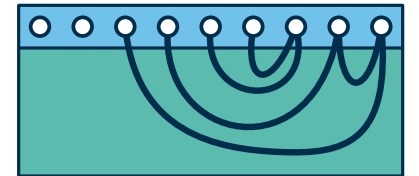


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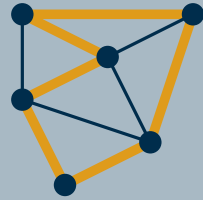
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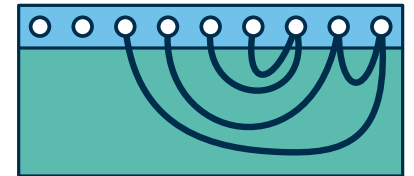


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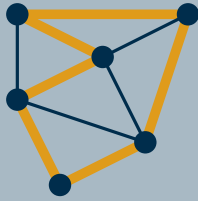
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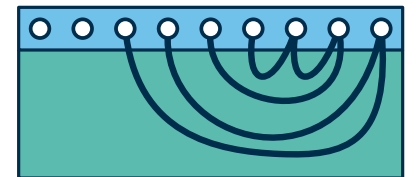
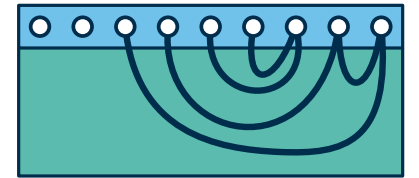


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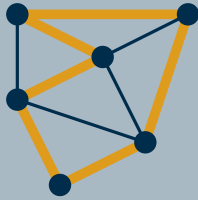
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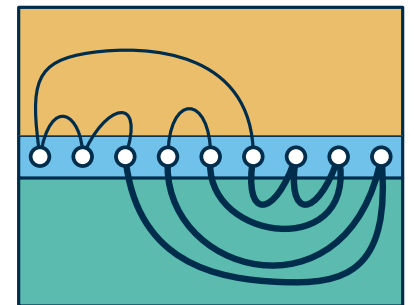
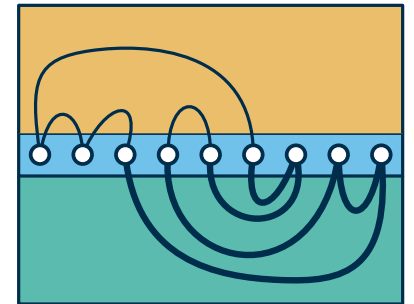


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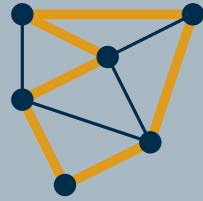
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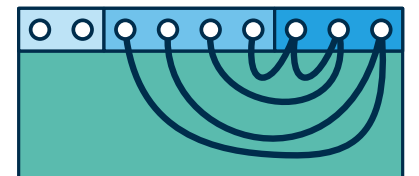
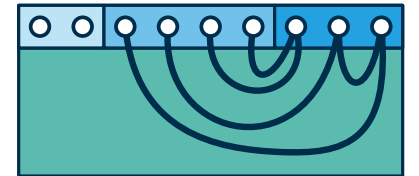


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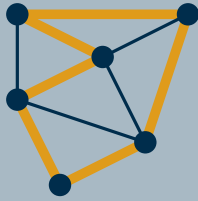
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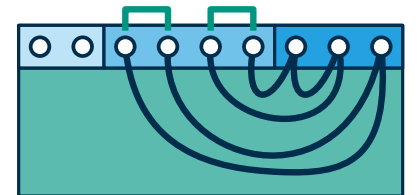
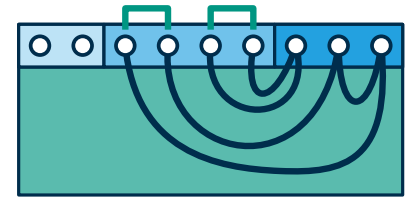


Goal

- FPT with respect to treewidth
- given: corresponding tree decomposition

What is a useful definition for partial solutions?

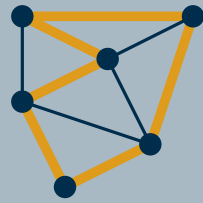
- observation: Hamiltonian cycle in G yields a set of paths in G_i
- define partial solution (first try): set of paths in G_i between interface vertices
- problem: too many sets of paths
- observation: different path sets are indistinguishable from the outside, if
 - same vertices of the interface incident to 0, 1, and 2 selected edges
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DP for Hamiltonian cycle – partial solutions

Problem: HAMILTONIAN CYCLE

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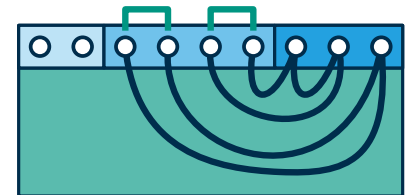
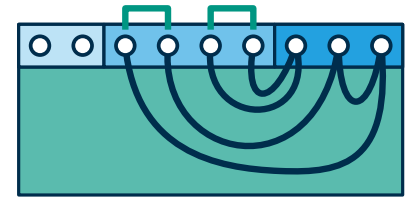
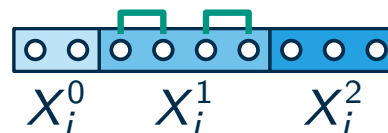


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 - same vertices of the interface incident to 0, 1, and 2 selected edges
 - the same pairs of 1-vertices are matched by paths
- define partial solution: partition of X_i into $X_i = X_i^0 \cup X_i^1 \cup X_i^2$ and matching on X_i^1

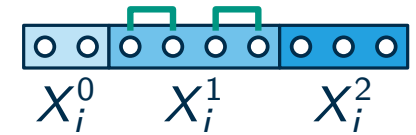


DP for Hamiltonian cycle – forget node

What does the DP do in general?

- process nodes bottom up
- when node is processed: assume all children have been processed

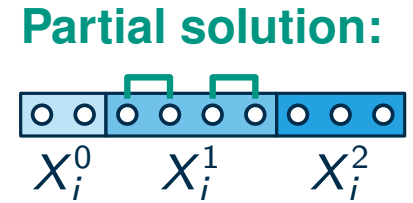
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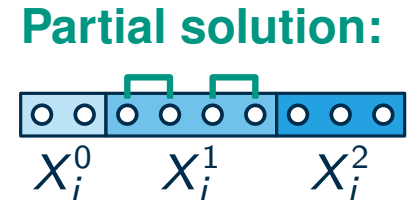
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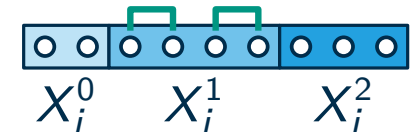
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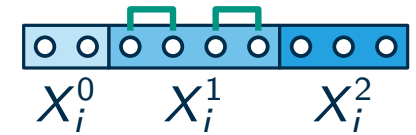


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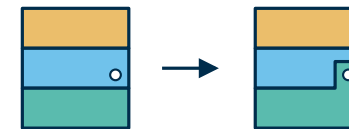


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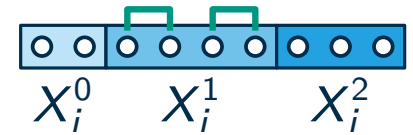
Computing new partial solutions: forget node

- let v be the vertex that is forgotten



DP for Hamiltonian cycle – forget node

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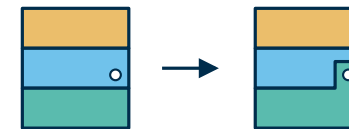


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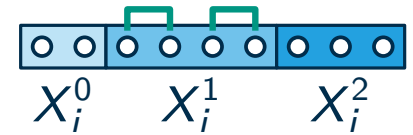
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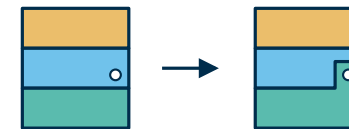


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Computing new partial solutions: forget node

- let v be the vertex that is forgotten
- if $v \in X_i^2$:



- if $v \notin X_i^2$:
 - v has no chance to be part of the Hamiltonian cycle
 - dead end \rightarrow ignore this partial solution of the child

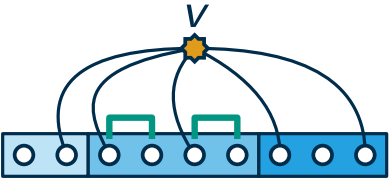
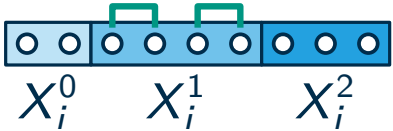
DP for Hamiltonian cycle – introduce node

Computing new partial solutions: introduce node

- let v be the introduced vertex and consider its edges to the interface X_i



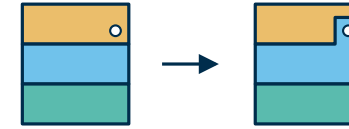
Partial solution:



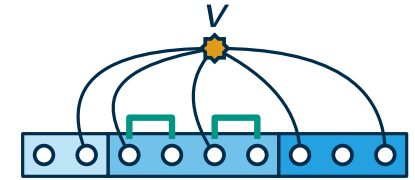
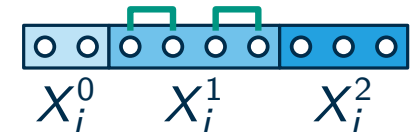
DP for Hamiltonian cycle – introduce node

Computing new partial solutions: introduce node

- let v be the introduced vertex and consider its edges to the interface X_i
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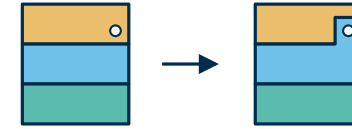
Partial solution:



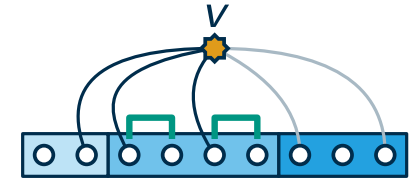
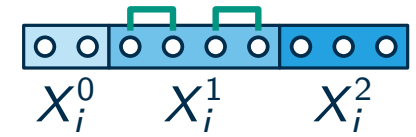
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Computing new partial solutions: introduce node

- let v be the introduced vertex and consider its edges to the interface X_i
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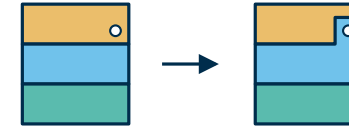
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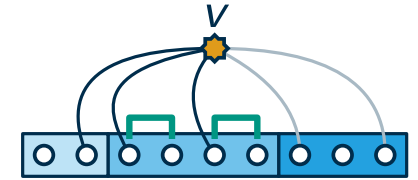
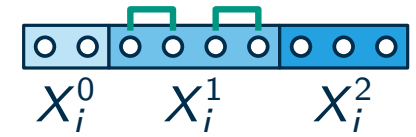
DP for Hamiltonian cycle – introduce node

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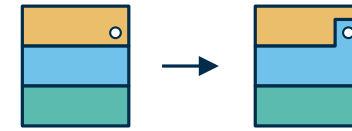
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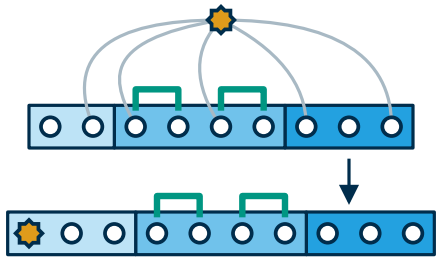
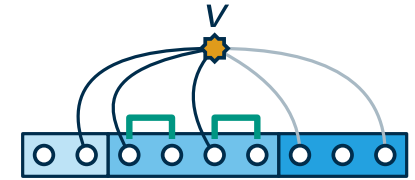
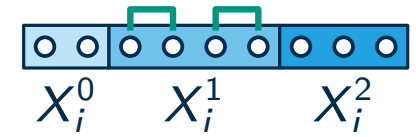
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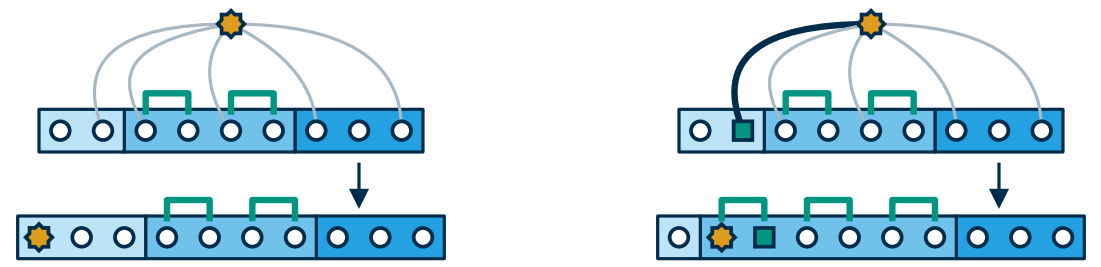
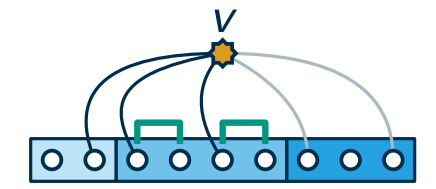
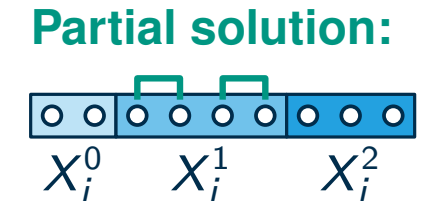
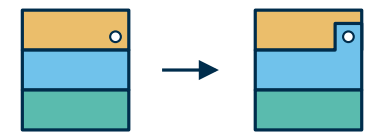
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DP for Hamiltonian cycle – introduce node

Computing new partial solutions: introduce node

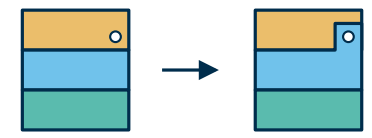
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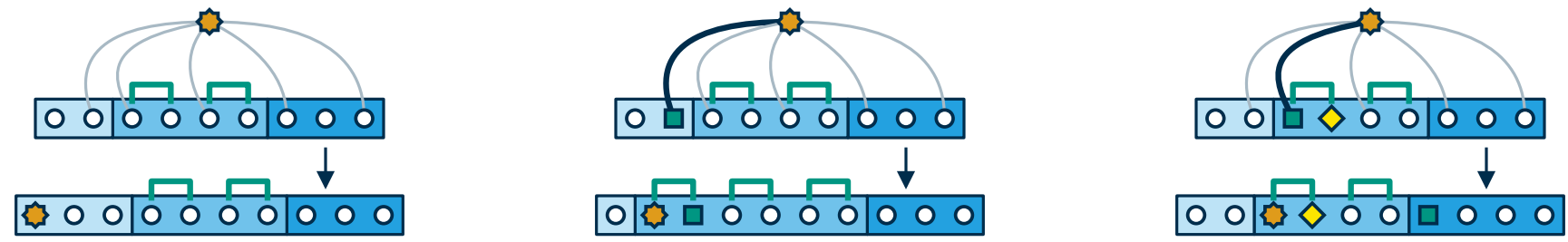
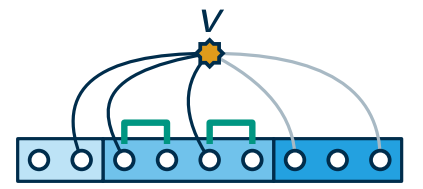
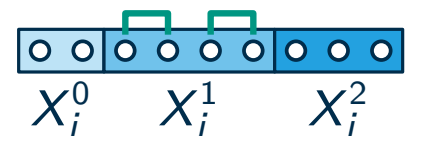
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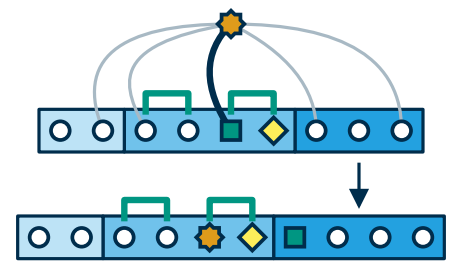
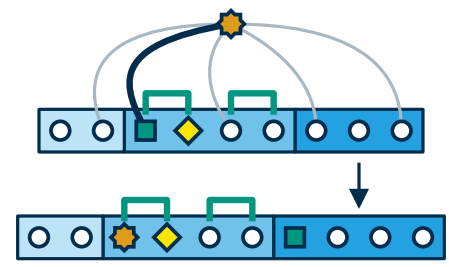
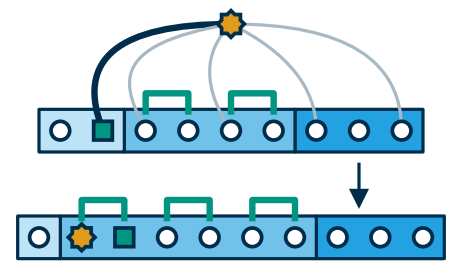
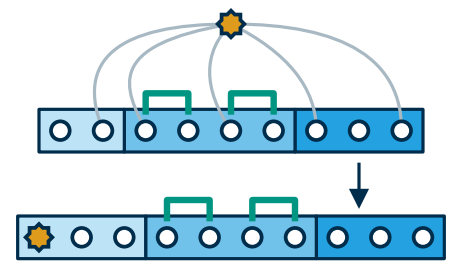
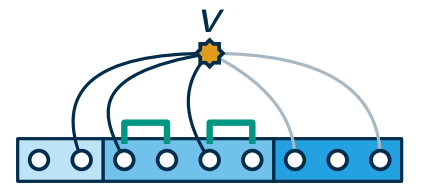
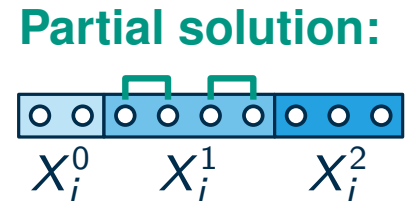
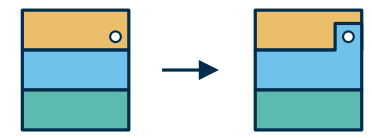
Partial solution:



DP for Hamiltonian cycle – introduce node

Computing new partial solutions: introduce node

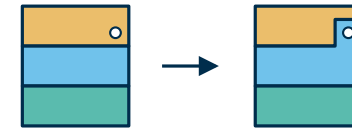
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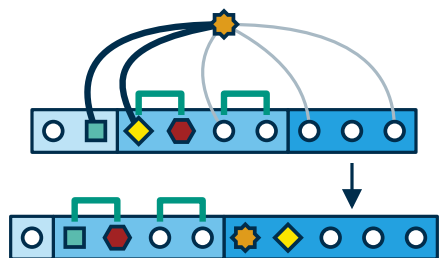
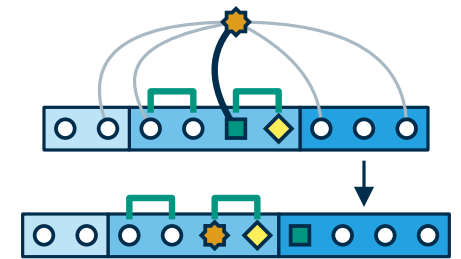
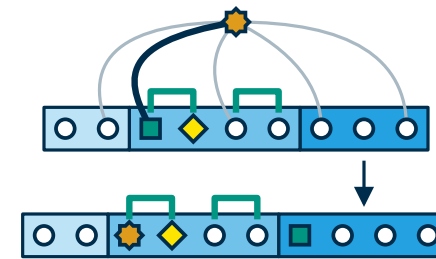
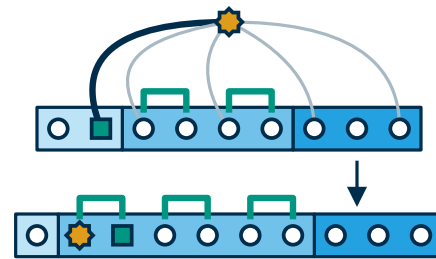
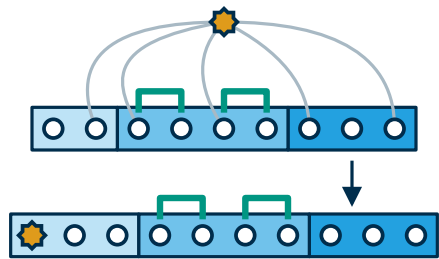
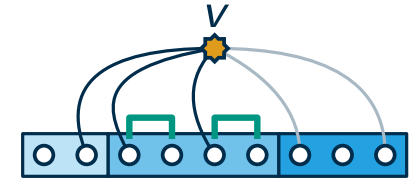
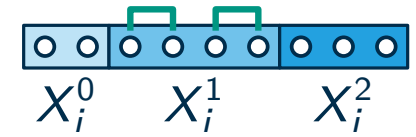
DP for Hamiltonian cycle – introduce node

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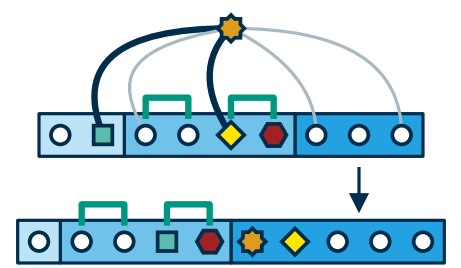
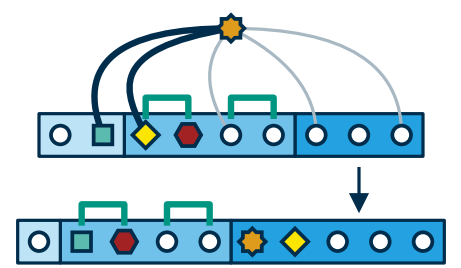
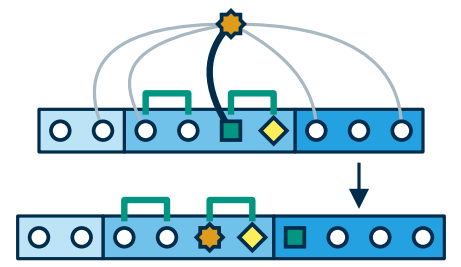
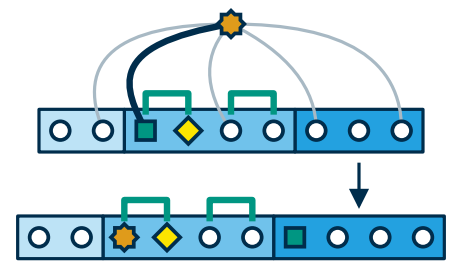
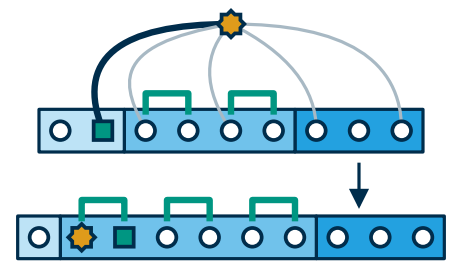
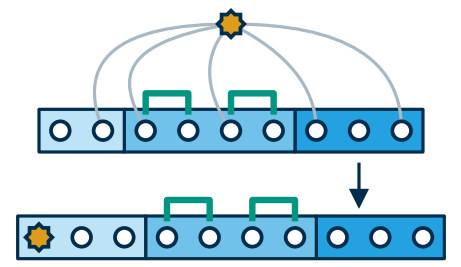
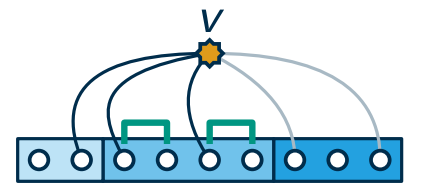
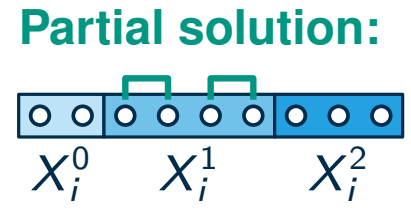
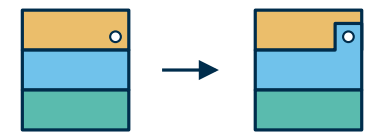
Partial solution:



DP for Hamiltonian cycle – introduce node

Computing new partial solutions: introduce node

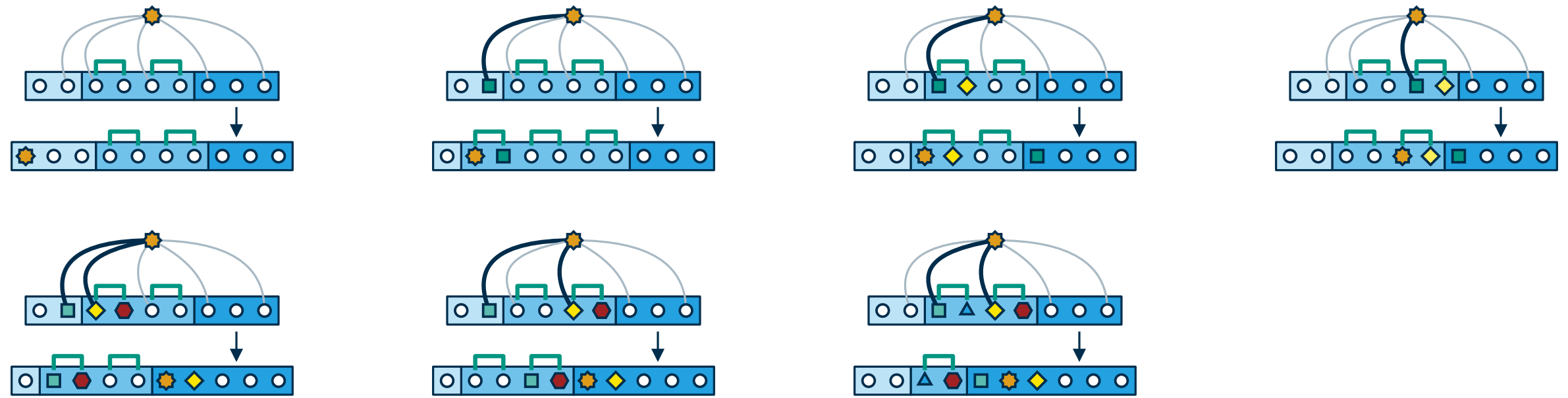
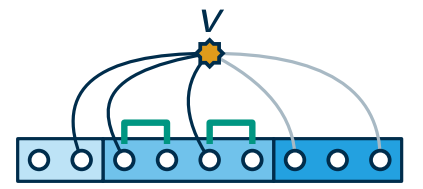
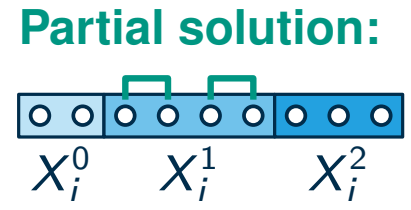
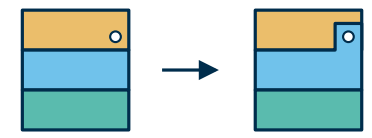
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DP for Hamiltonian cycle – introduce node

Computing new partial solutions: introduce node

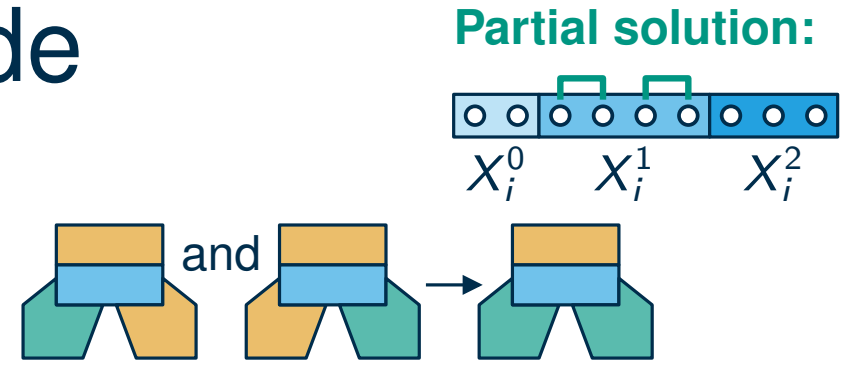
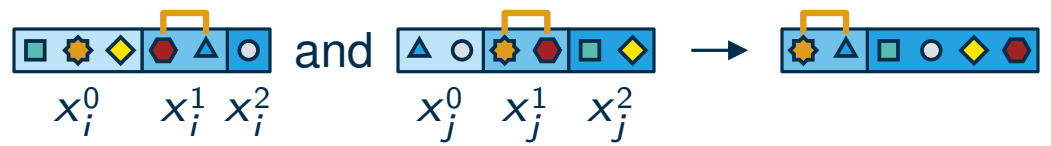
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DP for Hamiltonian cycle – join node

Computing new partial solutions: join node

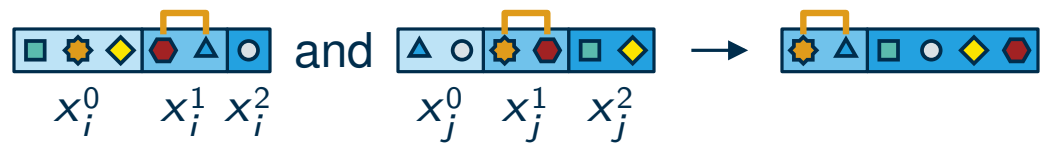
- combining two partial solutions → union of selected edges



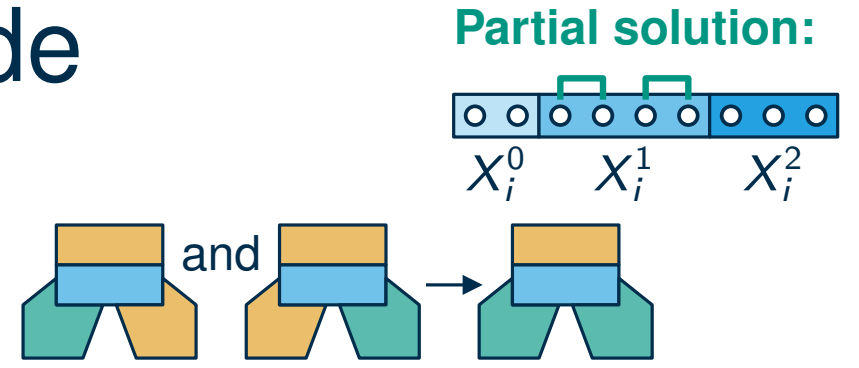
DP for Hamiltonian cycle – join node

Computing new partial solutions: join node

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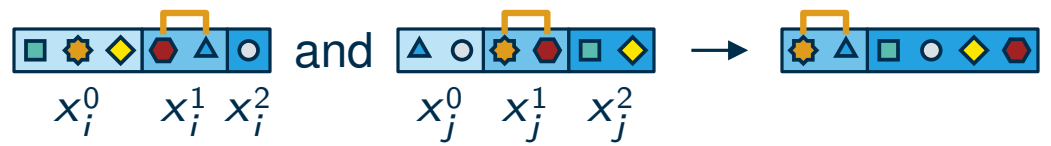
- union not possible if:



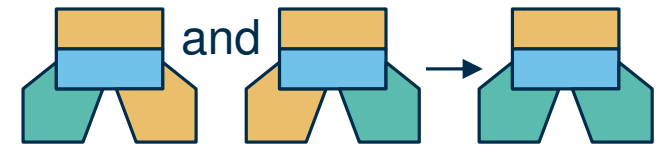
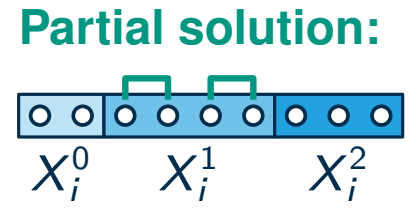
DP for Hamiltonian cycle – join node

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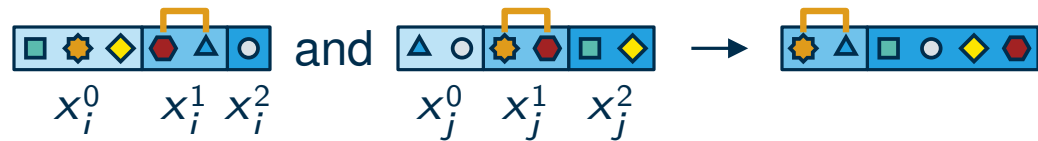
- union not possible if:
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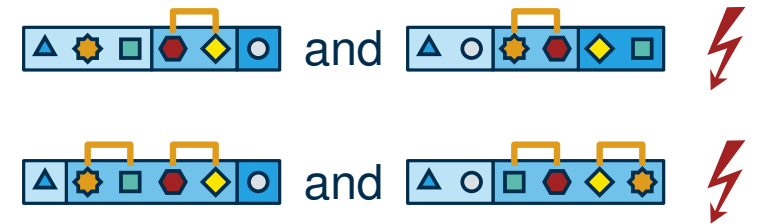
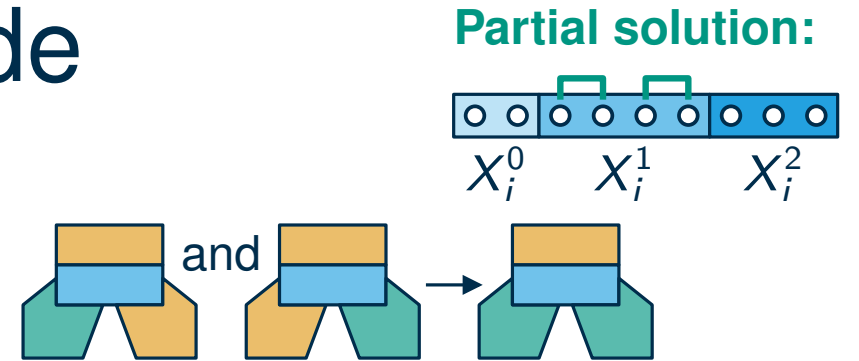
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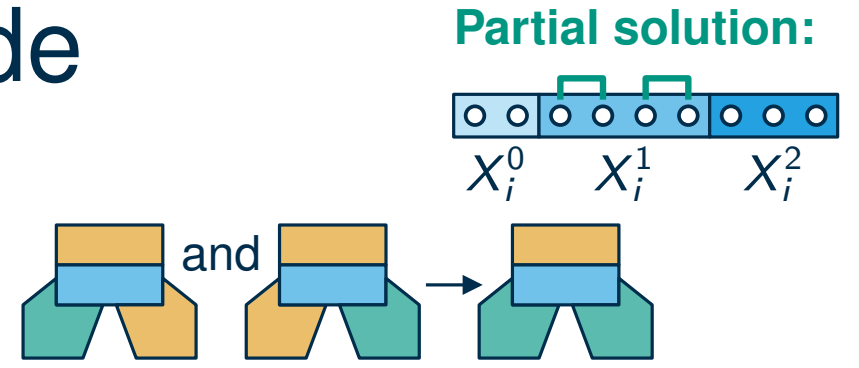
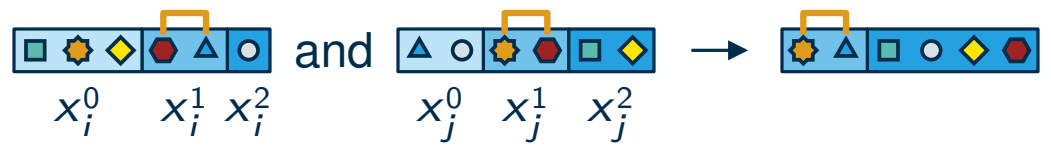
- for a vertex, the sum of degrees in G_i and G_j is > 2
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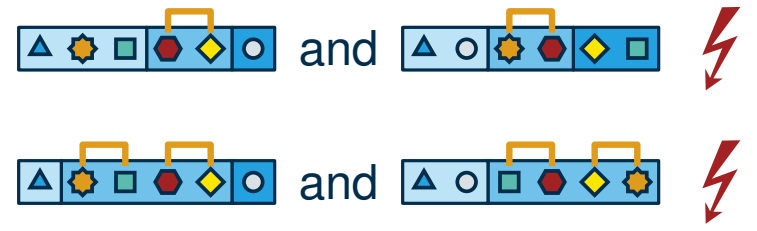
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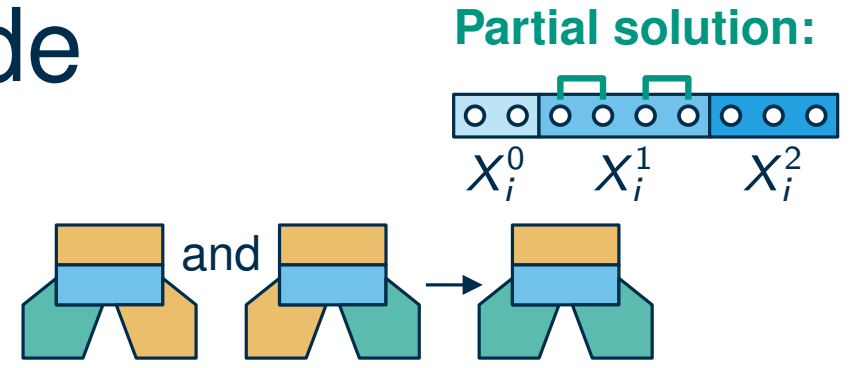
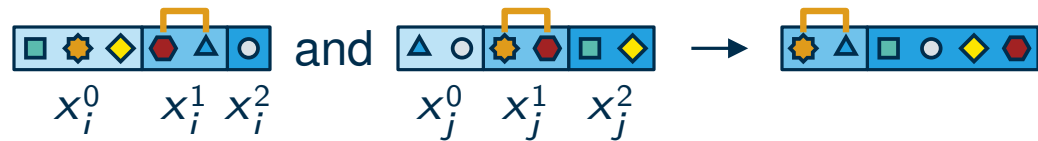
(special case: in the root x_r , we want to create a single cycle such that all vertices are in X_r^2)



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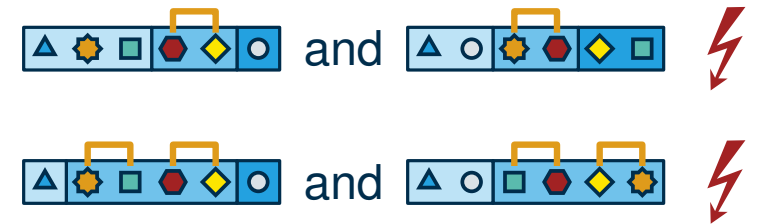
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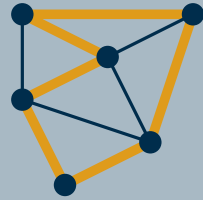
- otherwise:

- sum the vertex degrees to get the partition
- compute which pairs of 1-vertices belong to the same path

DP for Hamiltonian cycle

Problem: HAMILTONIAN CYCLE

Given a graph G . Does G have a cycle that visits all vertices?



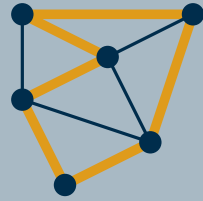
Goal

- FPT with respect to treewidth
- given: corresponding tree decomposition

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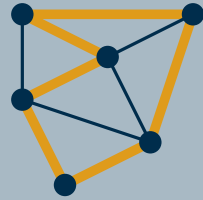
Is the DP's running time FPT?

- for each tree-node: number of partial solutions only depends on bag (aka interface) size
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Theorem

HAMILTONIAN PATH is FPT with respect to the treewidth t . (assuming we know a corresponding composition)

Wrap-UP

Treewidth

- structural graph parameter
- measures similarity to trees
(in regards to separators)



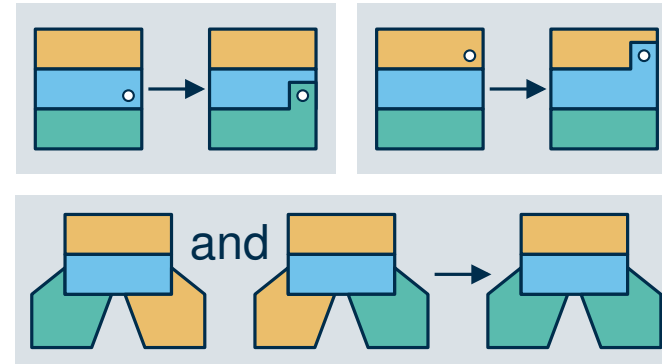
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DP on a tree decomposition

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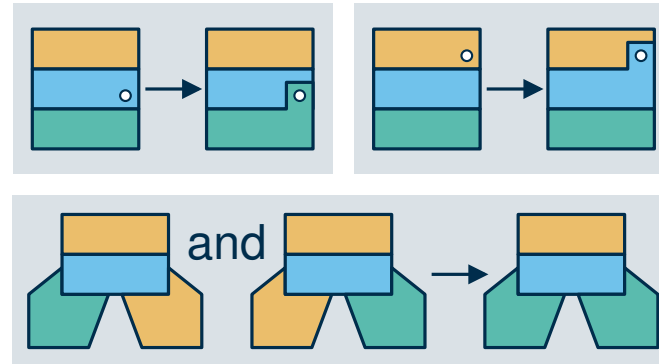
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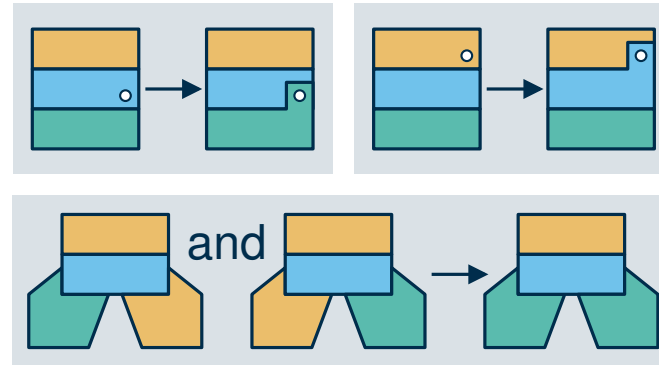
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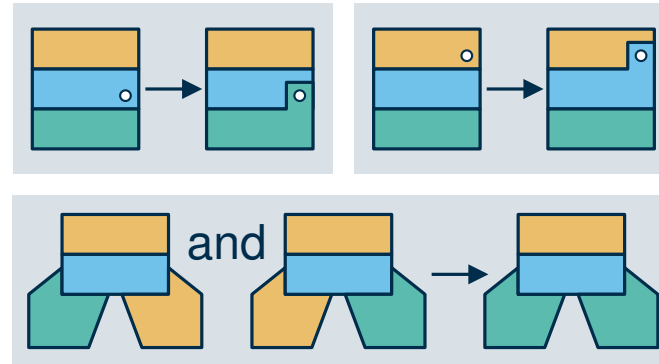
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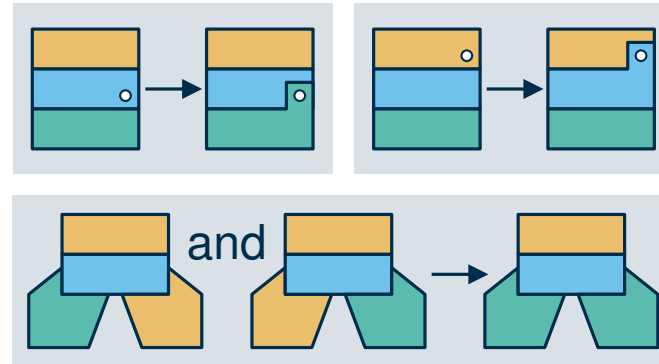
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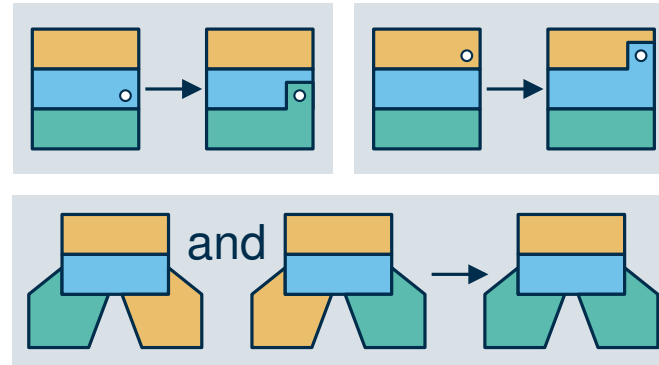
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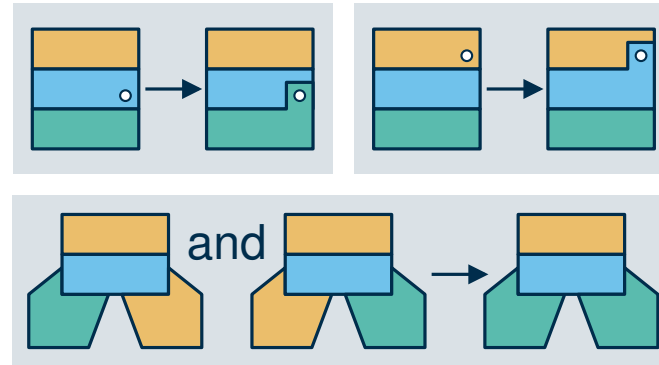
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