

# Computational Geometry Exercise 2

Jean-Pierre, Marcus, Wendy

# Assignment Sheet 1 – General comments

- please work in groups
- try to write clear and correct answers
  - for algorithms: always give reasoning for correctness, and running time
  - never give uncommented pseudocode, prefer natural language description
  - mention figures in the text





#### **Mysterious Meteorites**





 $m+n+2\min\{n,m\}$ 

#### **Convex Hull via Divide and Conquer**



Q: minimize barrier tape

### **Aerial Photography**



**Task:** Give algorithm to decide if  $p \in P$ .

**Map Overlay** 



**Boolean Operations Given:** Polygons P, Q**Task:** compute  $P \cap Q, P \cup Q$ , and  $(P \cup Q) \setminus (P \cap Q)$ 



#### **Mysterious Meteorites**



(b) (b) (b) (b)

 $m+n+2\min\{n,m\}$ 

#### **Convex Hull via Divide and Conquer**



Q: minimize barrier tape

### **Aerial Photography**



**Task:** Give algorithm to for the decide if  $p \in P$ .

**Map Overlay** 



**Boolean Operations Given:** Polygons P, Q**Task:** compute  $P \cap Q, P \cup Q$ , and  $(P \cup Q) \setminus (P \cap Q)$ 

#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 1: obtain sorting, Andrew's algorithm



Q: minimize barrier tape

**Aerial Photography** 



**Task:** Give algorithm to decide if  $p \in P$ .

**Map Overlay** 



**Boolean Operations** Given: Polygons P, QTask: compute  $P \cap Q, P \cup Q$ , and  $(P \cup Q) \setminus (P \cap Q)$ 

#### **Mysterious Meteorites**



(b)

```
m+n+2\min\{n,m\}
```

### **Convex Hull via Divide and Conquer**

Variant 1: obtain sorting, Andrew's algorithm



Q: minimize barrier tape

**Aerial Photography** 



**Task:** Give algorithm to for the decide if  $p \in P$ .

Map Overlay



#### **Mysterious Meteorites**



(b) (b) (b) (b)

 $m+n+2\min\{n,m\}$ 

#### **Convex Hull via Divide and Conquer**



Q: minimize barrier tape

### **Aerial Photography**



**Task:** Give algorithm to for the decide if  $p \in P$ .

**Map Overlay** 



**Boolean Operations Given:** Polygons P, Q**Task:** compute  $P \cap Q, P \cup Q$ , and  $(P \cup Q) \setminus (P \cap Q)$ 

#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 2: shoot ray from  $H_{\ell}$ , check if above  $H_r$ 



Q: minimize barrier tape

**Aerial Photography** 



**Task:** Give algorithm to for a decide if  $p \in P$ .

**Map Overlay** 



**Boolean Operations Given:** Polygons P, Q**Task:** compute  $P \cap Q, P \cup Q$ , and  $(P \cup Q) \setminus (P \cap Q)$ 

#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

#### **Convex Hull via Divide and Conquer**

Variant 2: shoot ray from  $H_{\ell}$ , check if above  $H_r$ 



Q: minimize barrier tape

**Aerial Photography** 



**Task:** Give algorithm to decide if  $p \in P$ .

**Map Overlay** 



#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 2: shoot ray from  $H_{\ell}$ , check if above  $H_r$ 



Q: minimize barrier tape

**Aerial Photography** 



**Task:** Give algorithm to decide if  $p \in P$ .

**Map Overlay** 



(b)

#### **Mysterious Meteorites**



Q: minimize barrier tape

**Aerial Photography** 



**Task:** Give algorithm to decide if  $p \in P$ .

 $m + n + 2\min\{n, m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 2: shoot ray from  $H_{\ell}$ , check if above  $H_r$ 



Map Overlay



**Boolean Operations Given:** Polygons P, Q**Task:** compute  $P \cap Q, P \cup Q$ , and  $(P \cup Q) \setminus (P \cap Q)$ 

#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 2: shoot ray from  $H_{\ell}$ , check if above  $H_r$ 



Q: minimize barrier tape

**Aerial Photography** 



**Task:** Give algorithm to decide if  $p \in P$ .

**Map Overlay** 



#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Q: minimize barrier tape

**Aerial Photography** 



Map Overlay



#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Q: minimize barrier tape

**Aerial Photography** 



**Task:** Give algorithm to decide if  $p \in P$ .

**Map Overlay** 



**Boolean Operations** Given: Polygons P, QTask: compute  $P \cap Q, P \cup Q$ , and  $(P \cup Q) \setminus (P \cap Q)$ 

#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Q: minimize barrier tape

**Aerial Photography** 



**Task:** Give algorithm to decide if  $p \in P$ .

**Map Overlay** 



**Boolean Operations Given:** Polygons P, Q**Task:** compute  $P \cap Q, P \cup Q$ , and  $(P \cup Q) \setminus (P \cap Q)$ 

#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Q: minimize barrier tape

**Aerial Photography** 



**Map Overlay** 



**Boolean Operations Given:** Polygons P, Q**Task:** compute  $P \cap Q, P \cup Q$ , and  $(P \cup Q) \setminus (P \cap Q)$ 

#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Q: minimize barrier tape

**Aerial Photography** 



Task: Give

algorithm to decide if  $p \in P$ .

### **Map Overlay**





#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Q: minimize barrier tape

**Aerial Photography** 



**Task:** Give algorithm to for a decide if  $p \in P$ .

**Map Overlay** 



**Boolean Operations Given:** Polygons P, Q**Task:** compute  $P \cap Q, P \cup Q$ , and  $(P \cup Q) \setminus (P \cap Q)$ 

(b)

#### **Mysterious Meteorites**



 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Q: minimize barrier tape

### **Aerial Photography**



Idea: count intersections of *P* with ray starting at *p* 

#### **Map Overlay**



#### **Mysterious Meteorites**



 $m + n + 2 \min l$ 

(b)

 $m + n + 2\min\{n, m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Q: minimize barrier tape

### **Aerial Photography**



Idea: count intersections of *P* with ray starting at *p*  **Map Overlay** 



#### **Mysterious Meteorites**



 $m + n + 2 \min\{n, m\}$ 

(b)

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Q: minimize barrier tape

### **Aerial Photography**



Idea: count intersections of *P* with ray starting at *p* 

### **Map Overlay**



#### **Mysterious Meteorites**



(b)

 $m+n+2\min\{n,m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Q: minimize barrier tape

### **Aerial Photography**



**Idea:** count intersections of *P* with ray starting at *p*  **Map Overlay** 



(b)

#### **Mysterious Meteorites**



Q: minimize barrier tape

### **Aerial Photography**



**Edge-cases:** count intersection of ray with  $\overline{ab} \in P$ , where (wlog) *a* on ray only if *b* below ray

 $m + n + 2\min\{n, m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



Map Overlay



(b)

#### **Mysterious Meteorites**



Q: minimize barrier tape

**Aerial Photography** 



**Edge-cases:** count intersection of ray with  $\overline{ab} \in P$ , where (wlog) *a* on ray only if *b* below ray

 $m + n + 2\min\{n, m\}$ 

### **Convex Hull via Divide and Conquer**

Variant 3: move candidate tangent iteratively



**Map Overlay** 



Map Overlay1. update edge pointers





Map Overlay1. update edge pointers





#### **Map Overlay**

1. update edge pointers









- 1. update edge pointers
- 2. update faces





- 1. update edge pointers
- 2. update faces





#### **Map Overlay**

- 1. update edge pointers
- 2. update faces

Find parent inner face of outer face *f* 





- 1. update edge pointers
- 2. update faces
  - Find parent inner face of outer face *f*





- 1. update edge pointers
- 2. update faces
  - Find parent inner face of outer face *f*





- 1. update edge pointers
- 2. update faces
  - Find parent inner face of outer face *f*





#### **Map Overlay**

- 1. update edge pointers
- 2. update faces

Find parent inner face of outer face *f* 

3. face labels

sweep-line





#### **Map Overlay**

1. update edge pointers

2. update faces

Find parent inner face of outer face *f* 

3. face labels

sweep-line

### **Boolean operations**

use labels of faces from map overlay





**Dangerous Walls** 



### **Triangulation**



Q: how many triangles? what if *P* contains holes?

### y-Monotone Triangulation

How to triangulate y-monotone Polygon in O(n)?



### Completing 2D Linear Programming $\chi_{\lambda}$

Given: 2D LP

**Decide:** are there solutions with arbitrarily large objective?



**Dangerous Walls** 



### **Triangulation**



Q: how many triangles? what if *P* contains holes?

#### y-Monotone Triangulation

How to triangulate y-monotone Polygon in O(n)?

(easier: assume no two vertices have same y-coordinate)



### Completing 2D Linear Programming

Given: 2D LP

**Decide:** are there solutions with arbitrarily large objective?



**Problem: Range Reporting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $P \cap B$ 





**Problem: Range Counting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $|P \cap B|$ 





**Problem: Range Counting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $|P \cap B|$ 

#### **Questions:**

• how to do this for d = 1? (running time? space?)



**Problem: Range Counting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $|P \cap B|$ 

#### **Questions:**

- how to do this for d = 1? (running time? space?)
- how to generalize for d ∈ N? compare with range reporting query!



**Problem: Range Counting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $|P \cap B|$ 

#### **Questions:**

- how to do this for d = 1? (running time? space?)
- how to generalize for d ∈ N? compare with range reporting query!
- improvement for d = 2?



**Problem: Range Counting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $|P \cap B|$ 

#### **Questions:**

- how to do this for d = 1? (running time? space?)
- how to generalize for d ∈ N? compare with range reporting query!
- improvement for d = 2?
- improvement for d = 3?



**Problem: Range Counting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $|P \cap B|$ 

### **Questions:**

- how to do this for d = 1? (running time? space?)
- how to generalize for d ∈ N? compare with range reporting query!
- improvement for d = 2?
- improvement for d = 3?

**Problem: Range** *Rectangle* **Reporting Query** Input: set of rectangles  $R \subseteq \mathbb{R}^2$ , box  $B = [a_1, b_1] \times [a_d, b_d]$ Question: which rectangles are fully contained in *B*?





**Problem: Range Counting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $|P \cap B|$ 

### **Questions:**

- how to do this for d = 1? (running time? space?)
- how to generalize for d ∈ N? compare with range reporting query!
- improvement for d = 2?
- improvement for d = 3?





**Problem: Range** *Rectangle* **Reporting Query** Input: set of rectangles  $R \subseteq \mathbb{R}^2$ , box  $B = [a_1, b_1] \times [a_d, b_d]$ Question: which rectangles are fully contained in *B*?



**Problem: Range Counting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $|P \cap B|$ 

### **Questions:**

- how to do this for d = 1? (running time? space?)
- how to generalize for  $d \in \mathbb{N}$ ? compare with range reporting query!
- improvement for d = 2?
- improvement for d = 3?





**Problem: Range** *Rectangle* **Reporting Query** Input: set of rectangles  $R \subseteq \mathbb{R}^2$ , box  $B = [a_1, b_1] \times [a_d, b_d]$ Question: which rectangles are fully contained in *B*?

how to do this? (data structure, running time, space?) hint: uvtu-qvzrafvbany



**Problem: Range Counting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $|P \cap B|$ 

### **Questions:**

- how to do this for d = 1? (running time? space?)
- how to generalize for d ∈ N? compare with range reporting query!
- improvement for d = 2?
- improvement for d = 3?





Question: which rectangles are fully contained in B?

- how to do this? (data structure, running time, space?) hint: uvtu-qvzrafvbany
- what about Range Polygon Reporting?





**Problem: Range Counting Query** Input: set of points  $P \subseteq \mathbb{R}^d$ , box  $B = [a_1, b_1] \times \cdots \times [a_d, b_d]$ Task: compute  $|P \cap B|$ 

### **Questions:**

- how to do this for d = 1? (running time? space?)
- how to generalize for  $d \in \mathbb{N}$ ? compare with range reporting query!
- improvement for d = 2?  $O(\log n)$
- improvement for d = 3?

 $O(\log^2 n)$  or  $O(\log n + k)$ 

**Problem: Range** *Rectangle* **Reporting Query** Input: set of rectangles  $R \subseteq \mathbb{R}^2$ , box  $B = [a_1, b_1] \times [a_d, b_d]$ Question: which rectangles are fully contained in *B*?

- how to do this? (data structure, running time, space?) hint: uvtu-qvzrafvbany
  4-d queries in 4-d range tree!
- what about Range Polygon Reporting?



