

Computational Geometry

Real RAM, Word RAM, Point Location

What is a computer?

Thomas Bläsius

What Can Your Computer Do?

Model Of Computation

- RAM (random access machine): memory access in $O(1)$ via an address
- real RAM
 - every memory cell holds a real number (of arbitrary size/precision)
 - arithmetic operations $(+, -, \cdot, /)$ in $O(1)$
 - rounding to integers is **not** allowed (otherwise, you can do broken things)
 - common model in computational geometry → abstracts away precision issues
 - potential problem: sometimes too powerful (more powerful than your computer)
- word RAM
 - every memory cell holds a **word** consisting of w bits
 - w is sufficiently large ($\geq \log n$, but potentially much larger)
 - arithmetic operations on integers (of size up to 2^w) in $O(1)$
 - bit-wise logical operations and bit shifts in $O(1)$

Minimum Link Path In Polygons

Problem: Minimum Link Path

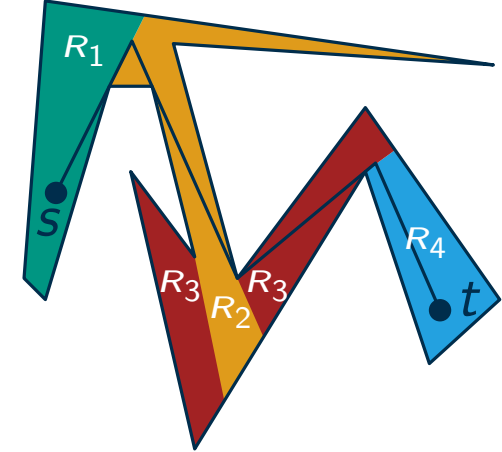
Given a polygon P as well as points s and t in P , compute an st -path inside P with the minimum number of segments.

Theorem (without proof)

The minimum link path between two points in a polygon of size n can be computed in $O(n)$ time.

Theorem (without proof)

There are instances encodable with $\Theta(n \log n)$ bits such that representing the polygons R_1, \dots, R_n requires $\Theta(n^2 \log n)$ bits.



General Idea

- R_i = set of points reachable from s with i links
- iteratively compute R_{i+1} from R_i

Which Of Them Is True?

- first theorem assumes a real RAM
- an implementations (e.g., with doubles for coordinates) is maybe not robust

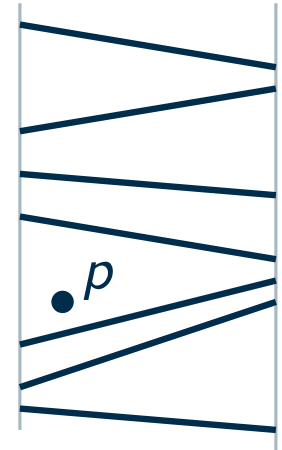
Point-Location In A Vertical Slab (word RAM)

Problem

Let S be a set of disjoint segments between two vertical lines. Build a data structure that can answer between which two segments a query point p lies. (with acceptable memory consumption)

Lets Start With One Dimension

- predecessor search in a sequence of numbers
- default solution: binary search provides $\Theta(\log n)$ queries
- goal: queries in $o(\log n)$
- use properties of the word RAM
 - numbers are integers
 - numbers lie in the interval $[0, 2^w)$
 - arithmetic operations, bit-wise logical operations, and bit-shifts on words of length w in $O(1)$



Beating The $\log n$ Lower Bound

Ideas For Improvement

- wider branching: shrink number of possible integers by the factor b in each step
 - recursion depth: $\log_b(n)$ (sub-logarithmic if b super-constant)
 - problem: decision for the correct subinterval too expensive
- shrinking the interval (in the beginning, all numbers lie in $[0, 2^w)$)
 - shrink the interval by the factor 2^h
 - recursion depth: $\frac{w}{h}$
 - problem: deciding whether a subinterval still contains integers
- combining both ideas
 - in each step: shrink the number of integers or the interval
 - decision for the correct interval: $O(1)$ with bit magic

Binary Search Basics

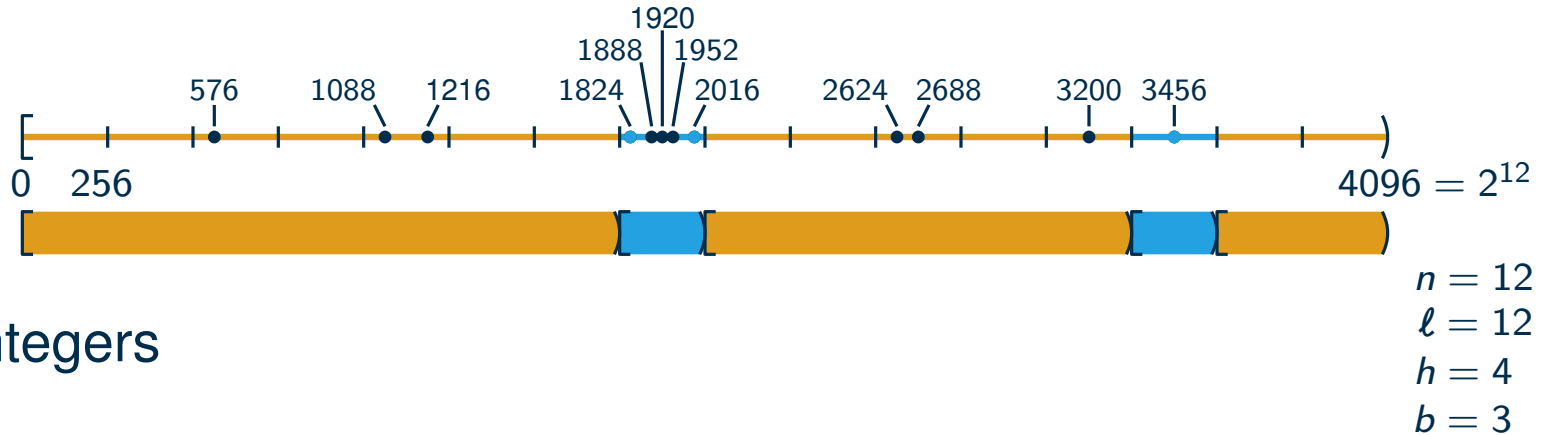
- walks down a decision tree
- decision for left/right subset: one comparison
- per step: number of integers is halved
- recursion depth: $\log_2(n)$

Subdivision Into Subintervals

word size: w
number of integers: n
interval: $[0, 2^\ell)$
number of cells: 2^h
branching width: b

One Subdivision Step

- divide interval of size 2^ℓ into 2^h cells of size $2^{\ell-h}$
- mark each $\frac{n}{b}$ th integer
- mark cells that contain marked integers
- define partition into subintervals
 - each marked cell is a subinterval
 - each maximal sequence of unmarked cells is a subinterval



Properties Of This Subdivision

- we have $O(b)$ subintervals
- the boundaries of each subinterval is a multiple of $2^{\ell-h}$
- each subinterval has length $2^{\ell-h}$ or contains at most $\frac{n}{b}$ integers

Recursive Subdivision

word size: w
number of integers: n
interval: $[0, 2^\ell)$
number of cells: 2^h
branching width: b

Lemma

(nice (h, b) -subdivision)

Given n integers in $I = [0, 2^\ell)$. I can be subdivided into $O(b)$ subintervals such that:

- each subinterval has length $2^{\ell-h}$ or contains at most $\frac{n}{b}$ integers
- the boundaries of the subintervals are multiples of $2^{\ell-h}$

Recursive Decision Tree

- one child for each subinterval in the (h, b) -subdivision
- stop recursion if only few integers are left
- height of the tree: at most $\log_b(n) + \frac{w}{h}$

Note: In the recursive calls, we may need to shift the subinterval to 0 and increase it to the next power of 2, such that it has the form $[0, 2^\ell)$.

Why?

Searching For The Successor Of An Integer q

- find subinterval containing q at most $\log_b(n) + \frac{w}{h}$ times
 - bit magic: each step runs in $O(1)$ if $\frac{w}{h} \geq \frac{b}{c}$ (for a constant c)
- $$\left. \vphantom{\begin{array}{l} \text{find subinterval containing } q \text{ at most } \log_b(n) + \frac{w}{h} \text{ times} \\ \text{bit magic: each step runs in } O(1) \text{ if } \frac{w}{h} \geq \frac{b}{c} \text{ (for a constant } c) \end{array}} \right\} \begin{array}{l} O(\log_b(n) + b) \text{ for } \frac{w}{h} = \frac{b}{c} \\ O\left(\frac{\log n}{\log \log n}\right) \text{ for } b = \sqrt{\log n} \end{array}$$

How Many Bits Do You Need?



How many bits are necessary in total to encode the numbers b , r , e , a , k ?

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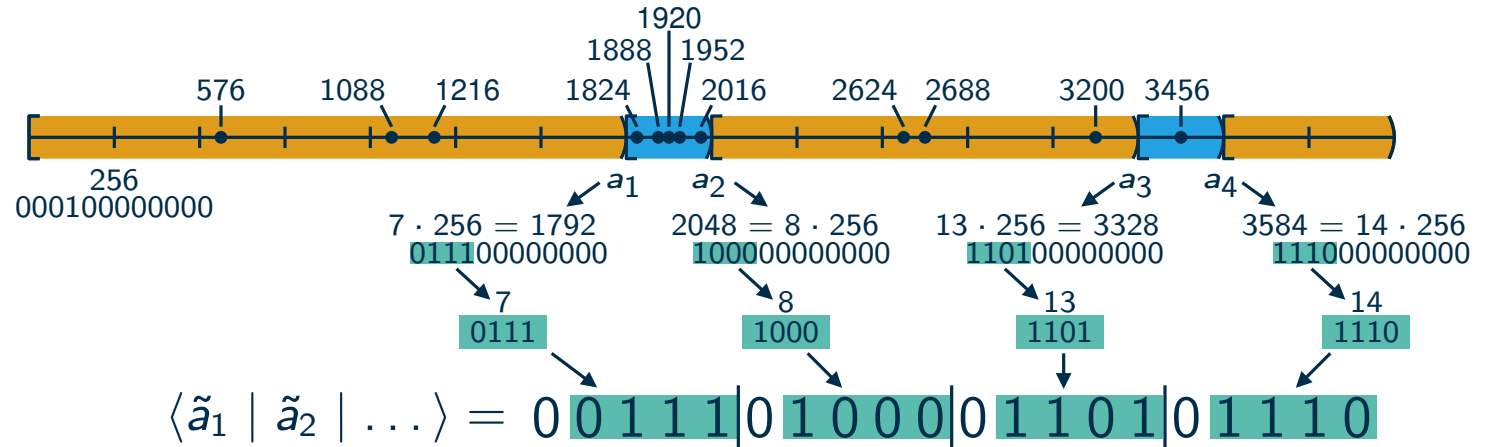
$$\begin{array}{lcl} b = 3 \cdot 256 & \longrightarrow & \boxed{0011}00000000 \\ r = 6 \cdot 256 & \longrightarrow & \boxed{0110}00000000 \\ e = 7 \cdot 256 & \longrightarrow & \boxed{0111}00000000 \\ a = 10 \cdot 256 & \longrightarrow & \boxed{1010}00000000 \\ k = 15 \cdot 256 & \longrightarrow & \boxed{1111}00000000 \end{array} \left. \vphantom{\begin{array}{l} b \\ r \\ e \\ a \\ k \end{array}} \right\} \boxed{0011} \mid \boxed{0110} \mid \boxed{0111} \mid \boxed{1010} \mid \boxed{1111}$$

20 bits

Representing The Subintervals

word size: w
 number of integers: n
 interval: $[0, 2^\ell)$
 number of cells: 2^h
 branching width: b

$n = 12$
 $\ell = 12$
 $h = 4$
 $b = 3$



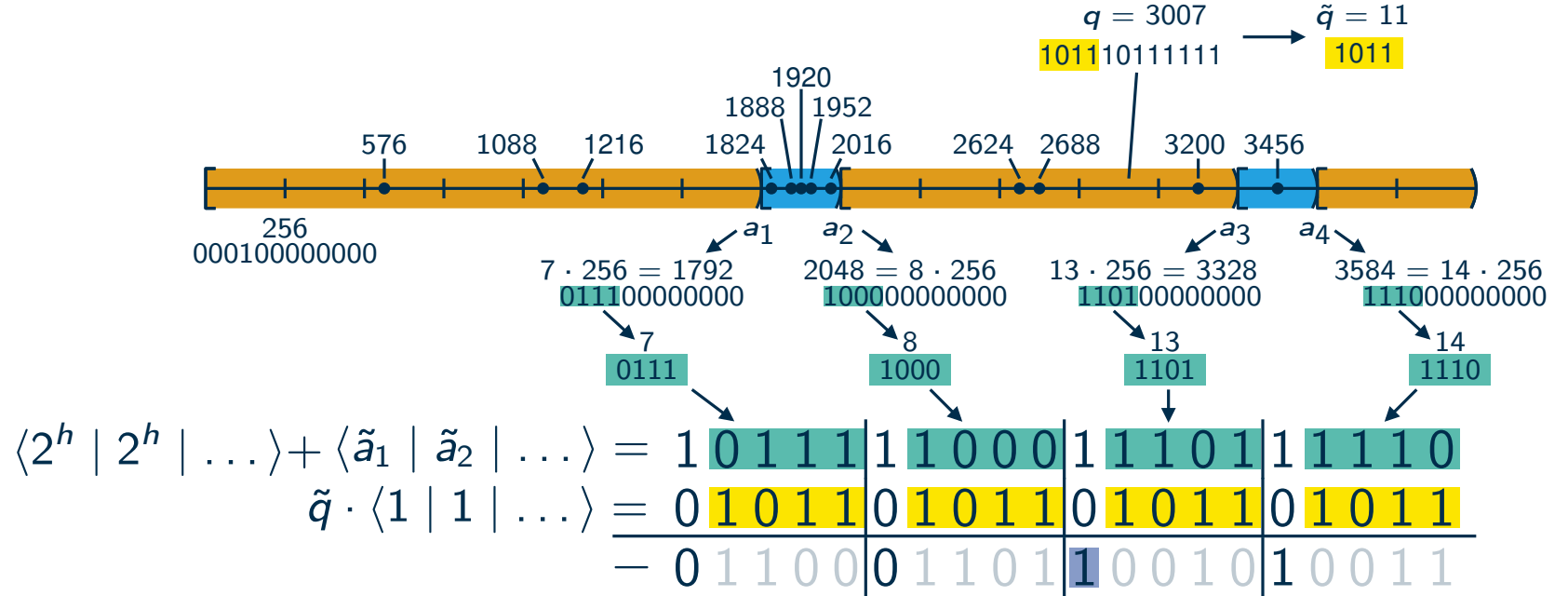
Representing The \bar{b} Interval Boundaries $a_1, \dots, a_{\bar{b}}$

- boundaries are multiples of $2^{\ell-h}$
- divide by $2^{\ell-h} \rightarrow$ result is $\leq 2^h$
- concatenate binary representation: $h \cdot \bar{b}$ bits
- spend one extra bit per boundary $\rightarrow (h + 1) \cdot \bar{b}$ bits
- assume $(h + 1) \cdot \bar{b} \leq w \rightarrow$ requires just one word (recall: we assumed things to work if $\frac{w}{h} \geq \frac{b}{c}$ for a constant c)
- store the resulting word $\langle \tilde{a}_1 \mid \tilde{a}_2 \mid \dots \rangle$ at the corresponding node in the recursion tree

Finding The Right Subinterval

word size: w
 number of integers: n
 interval: $[0, 2^\ell)$
 number of cells: 2^h
 branching width: b

$n = 12$
 $\ell = 12$
 $h = 4$
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Query: Which Subinterval Contains q ?

- find $\tilde{q} = \lfloor q/2^{\ell-h} \rfloor$ in $\{\tilde{a}_1, \tilde{a}_2, \dots\}$ instead (division by $2^{\ell-h}$ preserves order)
- it holds that: $\tilde{a}_i < \tilde{q} \Leftrightarrow (2^h + \tilde{a}_i - \tilde{q}) \& 2^h = 0$
- compute: $(\langle 2^h | 2^h | \dots \rangle + \langle \tilde{a}_1 | \tilde{a}_2 | \dots \rangle - \tilde{q} \cdot \langle 1 | 1 | \dots \rangle) \& \langle 2^h | 2^h | \dots \rangle$
- most of it can be **precomputed** $\rightarrow O(1)$ ($1 \times$ subtraction, $1 \times$ multiplication, $1 \times$ bit-wise $\&$)
- the **most significant 1-bit** yields i , such that $a_{i-1} < q \leq a_i$ (MS1B computable with $O(1)$ elementary operations)

Why?

Recap

word size: w
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Searching For The Successor Of An Integer q

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1D Search \rightarrow 2D Search

1D: In Each Node Of The Searchtree

- $O(b)$ boundaries, each a multiple of $2^{\ell-h}$
- subintervals: small ($2^{\ell-h}$) or few integers ($\frac{n}{b}$)

Why Does This Help?

h bits per boundary \rightarrow fit in just one word
sufficient progress in each node

1D: Query

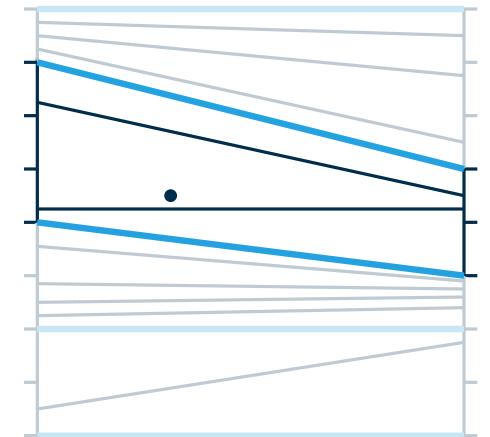
- search neighboring boundary
- continue in corresponding subtree

works in $O(1)$

happens $\leq \log_b(n) + \frac{w}{h}$ times

Extension To Point Location In A Slab

- choose boundaries with similar properties
- query a point (x, y)
 - 1D search with respect to y at the position x
 - round all coordinates $\rightarrow h$ bits per coordinate
- recursive call between boundaries



Problem: What if boundaries intersect the segments?

Nice Subdivision

Lemma

(nice (h, b) -subdivision)

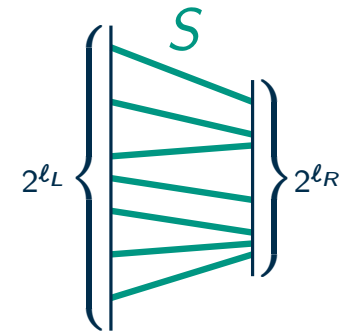
There are $O(b)$ boundary segments $s_0, s_1, \dots \in S$ such that

- between s_i and s_{i+1} there are $\leq \frac{n}{b}$ segments from S or $y_L(s_{i+1}) - y_L(s_i) < 2^{\ell_L - h}$ or $y_R(s_{i+1}) - y_R(s_i) < 2^{\ell_R - h}$
- $\tilde{s}_0 \prec s_0 \prec \tilde{s}_2 \prec s_2 \prec \dots$ for “rounded” boundaries \tilde{s}_i

Proof: exercise

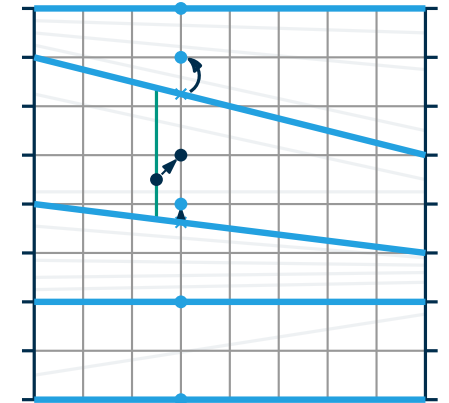
Notes On Running The Query For A Point $q = (x, y)$

- left/right endpoints of all \tilde{s}_i can be packed into just one word
- the (rounded) intersections of all \tilde{s}_i with a vertical line at \tilde{x} are computable with $O(1)$ operations
- searching on the rounded intersections for \tilde{y} as in the 1D case
- un-rounding: position of \tilde{q} in the $\tilde{s}_i \rightarrow$ position of q in the s_i (only $O(1)$ additional comparisons)



Input

- two vertical line segments that have length 2^{ℓ_L} and 2^{ℓ_R}
- n disjoint segments S between the two vertical segments



Wrap-Up

Seen Today

- models of computation: word RAM and real RAM
- real RAM often useful for computational geometry (but high precision sometimes unrealistic)
- bounded precision of the word RAM can be useful:
 - search and point location in vertical slab in $O(\frac{\log n}{\log \log n})$

What Else Is There?

- general point location with $o(\log n)$ queries in the word RAM
- problems with $o(n \log n)$ solutions on the word RAM:
 - 3D convex hull
 - Voronoi diagram
 - Euclidean MST
 - triangulation of polygons
 - line segment intersection

Literature

- **Transdichotomous Results in Computational Geometry, I:
Point Location in Sublogarithmic Time** (2009)
Timothy Chan, Mihai Pătraşcu
<https://doi.org/10.1137/07068669X>
- **Transdichotomous Results in Computational Geometry, II:
Offline Search** (2010)
Timothy Chan, Mihai Pătraşcu
<https://arxiv.org/abs/1010.1948>
- **On the bit complexity of minimum link paths:
Superquadratic algorithms for problem solvable in linear time** (1999)
Simon Kahana, Jack Snoeyink
[https://doi.org/10.1016/S0925-7721\(98\)00041-8](https://doi.org/10.1016/S0925-7721(98)00041-8)